

# RIEGL VZ<sup>®</sup>-6000

- *more than 6,000 m measurement range*
- *exceptionally well suited for measuring snowy and icy terrain*
- *wide field of view, 60° x 360°*
- *high speed data acquisition up to 222,000 meas. / second*
- *high accuracy, high precision ranging based on echo digitization and online waveform processing*
- *multiple target capability - unlimited number of targets*
- *optional waveform data output*
- *built-in calibrated digital camera*
- *on-board inclination sensors*
- *integrated L1 GPS receiver with antenna*
- *integrated compass*
- *built-in SSD data storage media*
- *compact and rugged design*

This new 3D VZ-Line Laser Scanner offers superior and unrivaled long range measurement performance of more than 6,000 m, reflectorlessly.

RIEGL's unique V-Line technology is based on echo digitization and online waveform processing. The VZ-6000 operates even in poor visibility and demanding multi target situations caused by dust, haze, rain, snow.

Due to its laser wavelength the instrument is exceptionally well-suited for measuring snowy and icy terrain.

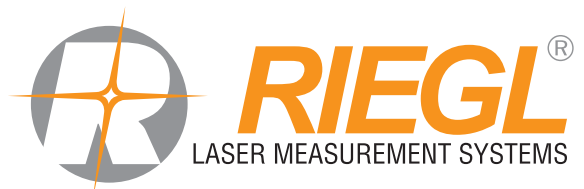
## Modes of Operation:

- stand-alone operation with integrated graphical user interface via 7" touchscreen
- remote control via VNC Viewer with any standard tablet PC or other mobile device via WiFi
- remote operation with RiSCAN PRO on a notebook via LAN or WiFi connection
- customized operation by third party tools / applications based on RIEGL's well documented interfaces and scanner libraries, e.g. RiVLib

## Typical applications include

- *Topography & Mining*
- *Glacier Mapping*
- *Snow Field Monitoring*
- *Long Range Monitoring*
- *Civil Engineering*
- *Archaeology*

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## Ultra Long Range Performance

The High-Speed, High-Resolution 3D Laser Scanner *RIEGL VZ-6000* offers an ultra long range of more than 6,000 m and a wide field of view of 60° vertical and 360° horizontal.

High accuracy and reliability of range measurement is based on *RIEGL's* unique V-Line technology of echo digitization and online waveform processing. Extreme long range measurements can be achieved even with poor visibility and demanding multi target situations caused by dust, haze, rain, snow, etc.

## Built-in Camera

A built-in calibrated 5-Megapixel camera capturing images deflected by the laser mirror allows coverage of the whole field of view with an appropriate number of high resolution images automatically stitched together to create a high resolution panorama image. This panorama image, in combination with precise 3D measurements produced by the VZ-6000, enables the creation of photorealistic virtual models for geological and geotechnical investigations, avalanche research, geomorphology, and geological features.

## Waveform Data Output (optional)

The digitized echo signals, acquired by the *RIEGL VZ-6000* - also known as waveform data - are the basis for waveform analysis. This data is provided via the optionally available waveform data output and accessible with the associated *RIEGL* software library RiWAVELib for investigations and research on multi target situations based on the digital waveform data samples of the target echoes.

## Designed for Demanding Fieldwork

3D profiling of the narrow infrared laser beam is realized with a light-weight vertically oscillating/rotating mirror which is mounted on a stable 360 degree horizontally rotateable mechanism.

This compact and rugged design with a dust- and splash-proof housing is the basis for long-term and reliable operation even under adverse environmental conditions.

## Compatible Software Packages

The *RIEGL VZ-6000* is compatible with the well-proven *RIEGL* software package RiSCANPRO for terrestrial laser scanning, *RIEGL's* interface library RiVLib, as well as the workflow-optimizing software packages RiMONITOR and RiMINING.

The software plugin RiMTA 3D provides automatic assignment of the correct MTA zones in multiple time around processing.

## Stand-alone Registration

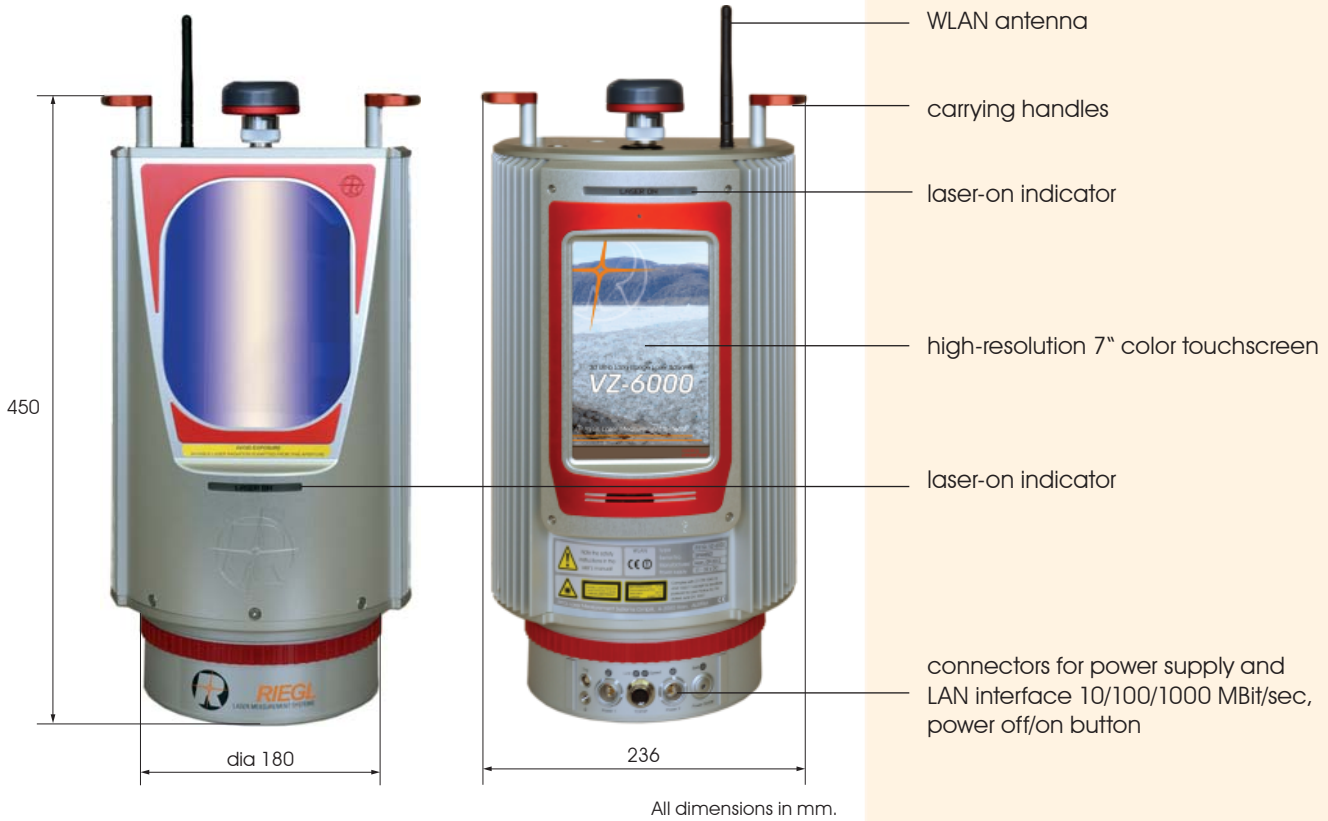
- integrated GPS receiver (L1) or external high-end GNSS receiver connected
- integrated compass, accuracy typ. 1° (one sigma value, available for vertical scanner setup position)
- on-board inclination sensors (tilt range  $\pm 10^\circ$ , accuracy typ.  $\pm 0.008^\circ$ )

## Registration via Control Points

- fast fine scanning of reflectors for precise determination of scanner position using control points

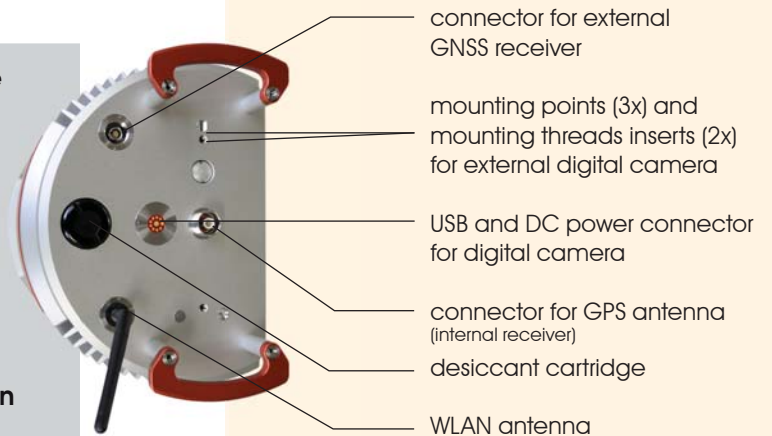
## Totalstation-like-Registration

- setup above well known point (integrated laser plummet)
- on-board inclination sensors
- precise fine scanning of well known remote target (reflector)
- Backsighting



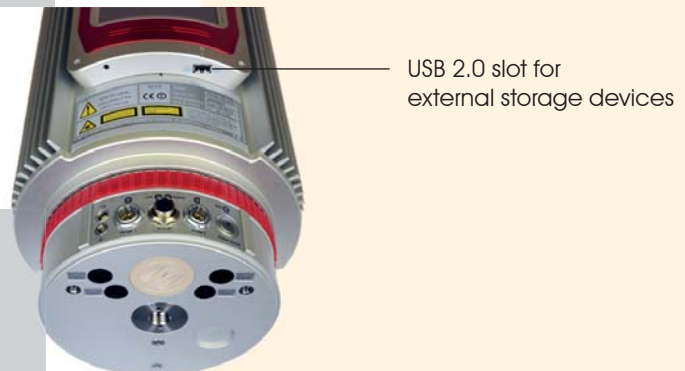
### Communication and Interfaces

- LAN port 10/100/1000 MBit/sec within base
- integrated WLAN interface with high-gain antenna
- USB 2.0 for connecting an external digital camera
- connector for GPS antenna
- two external power supply ports
- connector for external GPS synchronization pulse (1PPS)
- connector for external GNSS receiver



### Scan Data Storage

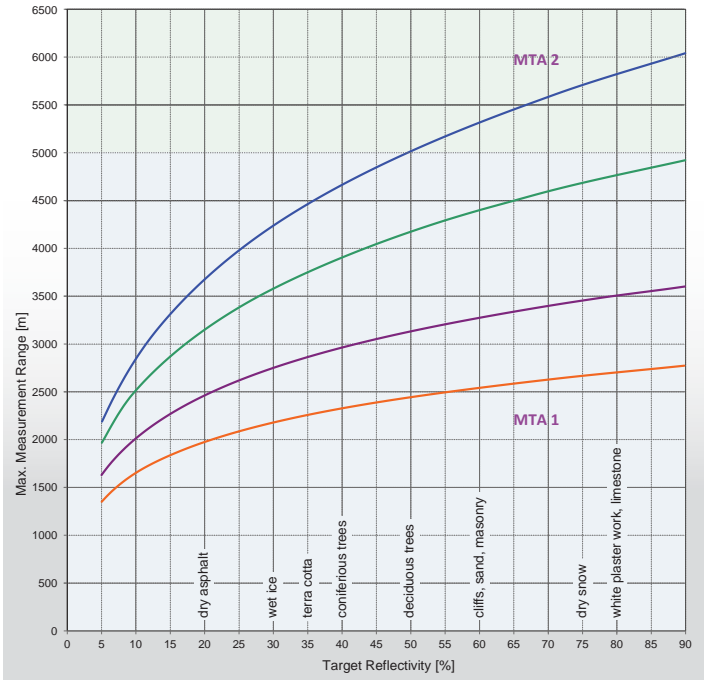
- internal 80 GByte SSD (Solid State Disc) (2 GByte reserved for the operating system)
- external storage devices (USB flash drives or external hard drives) via USB 2.0 interface



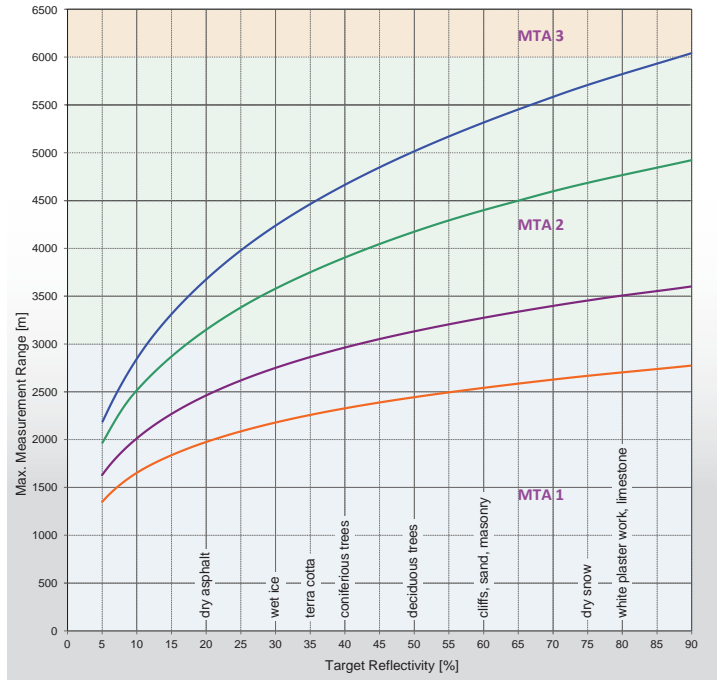


Blue	standard clear atmosphere: visibility 23 km
Green	clear atmosphere: visibility 15 km
Purple	light haze: visibility 8 km
Orange	medium haze: visibility 5 km

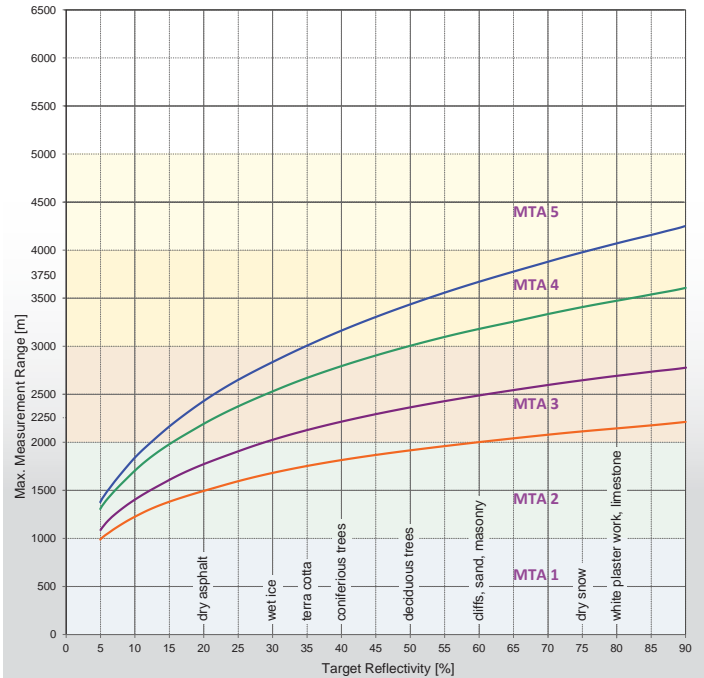
## 30 kHz PRR



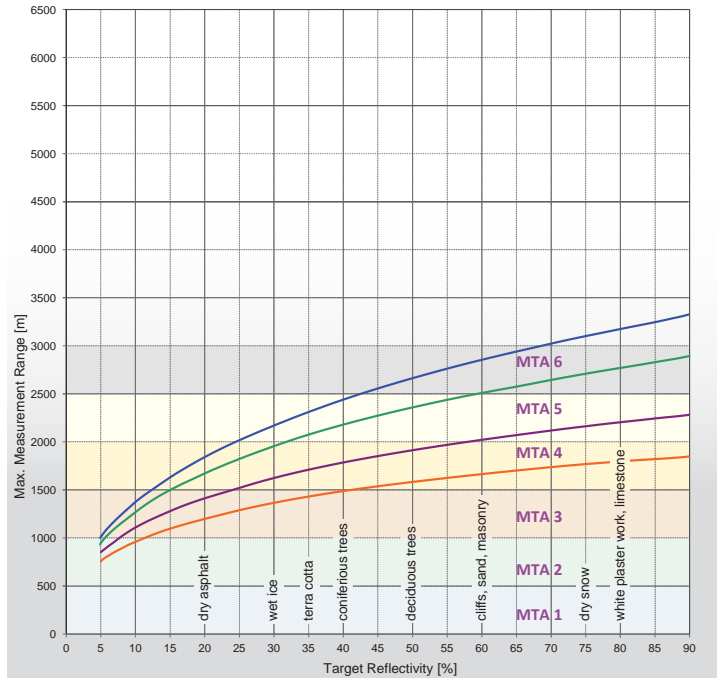
## 50 kHz PRR



## 150 kHz PRR



## 300 kHz PRR



### The following conditions are assumed:

- flat target larger than footprint of the laser beam
- perpendicular angle of incidence
- average brightness
- ambiguity resolved by post processing with RiMTA 3D

### MTA zones:

MTA 1: no ambiguity / 1 pulse „in the air“

MTA 2: 2 pulses „in the air“

MTA x: x pulses „in the air“

## User-Friendly and Efficient Operation and Acquisition Workflow

Operation is easy with the integrated graphical user interface via 7" touchscreen, or by remote control of the scanner via VNC Viewer with any tablet PC or mobile device via WiFi connection.

Highly efficient scan data acquisition and global registration is supported by on-board inclination sensors, integrated L1 GPS receiver, an interface for a high-end external GNSS receiver on top of the scanner, a digital compass and built-in SSD data storage media. With a visual project overview of acquired scan data, it is possible to ensure complete data coverage or check the progress of a project.



## Power Supply

### Add-on Rechargeable Battery

- optional add-on rechargeable battery pack (high power, high capacity NiMH cells)
- compact thin cylinder design, short-circuit-proof and protected connection pins
- rechargeable during standard scan operation via external power supply
- integrated micro-controller based charging electronics
- easily attachable to base of the laser scanner by central locking screw

### Power Supply

- intelligent power supply management, up to three independent external power sources can be connected simultaneously for uninterrupted operation
- reliable under- and over voltage protection
- wide external voltage supply range 11-32 V DC
- power consumption typ. 75 W (max. 90 W)
- LED indicators for power status



# Technical Data RIEGL VZ®-6000

## Laser Product Classification

The following clause applies for instruments delivered into the United States: Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 50, dated June 24, 2007

Class 3B Laser Product according to IEC60825-1:2007



## Range Measurement Performance <sup>1)</sup>

### Measuring Principle

### Mode of operation

time of flight measurement, echo signal digitization, online full waveform analysis, full waveform export capability (optional) single pulse ranging

Pulse repetition rate PRR (peak) <sup>2)</sup>	30 kHz	50 kHz	150 kHz	300 kHz
Effective Measurement Rate <sup>2)</sup>	23 000 meas./sec	37 000 meas./sec	113 000 meas./sec	222 000 meas./sec
Max. Measurement Range <sup>3)</sup>				
natural targets $\rho \geq 90\%$	6 000 m <sup>4)</sup>	6 000 m <sup>4)</sup>	4 200 m <sup>4)</sup>	3 300 m <sup>4)</sup>
natural targets $\rho \geq 20\%$	3 600 m	3 600 m <sup>4)</sup>	2 400 m <sup>4)</sup>	1 800 m <sup>4)</sup>
Max. Number of Targets per Pulse		practically unlimited <sup>5)</sup>		
NOHD (Nominal Ocular Hazard Distance) <sup>6)</sup>	85 m	85 m	45 m	28 m
ENOHD (Extended Nominal Ocular Hazard Distance) <sup>6)</sup>	1050 m	1050 m	690 m	245 m

### Accuracy <sup>7) 9)</sup>

15 mm

### Precision <sup>7) 9)</sup>

10 mm

### Minimum Range

5 m

### Laser Wavelength

near infrared

### Laser Beam Divergence

0.12 mrad <sup>10)</sup>

### Laser Beam Footprint (Gaussian Beam Definition)

15 mm @ exit, 60 mm @ 500 m, 120 mm @ 1000 m, 240 mm @ 2000 m

- 1) With online waveform processing.
- 2) Rounded values, selectable by measurement program.
- 3) Typical values for average conditions. Maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence and for atmospheric visibility of 23 km. In bright sunlight, the maximum range is shorter than under overcast sky.
- 4) Ambiguity to be resolved by post-processing.
- 5) Details on request.

- 6) (E)NOHD values only applicable for 3D scan patterns with minimum angular stepwidths  $\geq 0.01$  degree. Rectangular scan patterns with angular stepwidths  $< 0.01$  degree and/or line scans (2D scans) have higher (E)NOHD values.
- 7) Accuracy is the degree of conformity of a measured quantity to its actual (true) value.
- 8) Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result.
- 9) One sigma @ 150 m range under RIEGL test conditions.
- 10) Measured at the  $1/e^2$  points. 0.12 mrad corresponds to an increase of 12 mm of beam diameter per 100 m distance.

## Scanner Performance

### Scanning Mechanism

#### Vertical (Line) Scan

lightweight mirror  
rotating / oscillating / step-by-step  
total 60° (+30° / -30°)

#### Horizontal (Frame) Scan

rotating head

### Field of View (selectable)

100°/sec to 14,400°/sec ( $\pm 20$  rotations/sec), full FOV  
 $0.002^\circ \leq \Delta \theta \leq 0.280^\circ$  <sup>11)</sup>

max. 360°

### Scan Speed (selectable)

between consecutive laser shots

0°/sec to 60°/sec <sup>10)</sup>

### Angular Step Width $\Delta \theta$ (vertical), $\Delta \phi$ (horizontal)

better 0.0005° (1.8 arcsec)

$0.002^\circ \leq \Delta \phi \leq 3^\circ$  <sup>11)</sup>

### Angle Measurement Resolution

integrated, for vertical scanner setup position, details see page 2

between consecutive scan lines

### Inclination Sensors

integrated, L1, with antenna

better 0.0005° (1.8 arcsec)

### GNSS Receiver

integrated, for vertical scanner setup position, details see page 2

### Compass

integrated

### Laser Plummet

integrated, for real-time synchronized time stamping of scan data

### Internal Sync Timer

scanner rotation synchronization

### Scan Sync (optional)

providing digitized echo signal information for specific target echoes

### Waveform Data Output (optional)

10) Frame scan can be disabled, providing 2D scanner operation.

11) Selectable.

## Communication

### Interfaces

LAN port 10/100/1000 Mbit/sec in the base, integrated WLAN interface with high-gain antennas, connector for GPS antenna, 2 connectors for external power supply connector for external GNSS-timing signals, connector for external high-end GNSS receiver internal 80 GByte SSD, external storage devices (USB flash drives or external hard drives) via USB 2.0 interface

### Scan Data Storage

## General Technical Data

### Power Supply Input Voltage

11 - 32 V DC

### Current Consumption

typ. 75 W (max. 90 W)

### Main Dimensions / Weight

236 x 226.5 x 450 mm (length x width x height), approx. 14.5 kg

### Humidity

max. 80 % non condensing @ +31°C

### Protection Class

IP64, dust- and splash-proof

### Temperature Range

0°C up to +40°C (operation) / -10°C up to +50°C (storage)

## Integrated Digital Camera

field of view 7.2°x5.5° (v x h)

resolution 2560 x 1920 pixels (5 Mpixel), automatic exposure control

## Display

7" WVGA (800 x 480) color

capacitive touchscreen, full operation control for stand alone usage



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