

**Topo-Hydrographic Airborne Laser Scanning System**  
with Online Waveform Processing and Full Waveform Recording

# RIEGL VQ<sup>®</sup>-880-GH

- **designed for combined topographic and hydrographic airborne survey**
- **high accuracy ranging based on echo digitization and online waveform processing with multiple-target capability**
- **multiple-time-around processing for straightforward mission planning and operation**
- **concurrent full waveform output for all measurements for subsequent full waveform analysis**
- **high spatial resolution due to measurement rate of up to 550 kHz and high scanning speed of up to 160 scans/sec**
- **integrated inertial navigation system**
- **additional, fully integrated infrared laser scanner (optional)**
- **up to two integrated digital cameras**

**NEW**

- **form factor with reduced height optimized for helicopter integrations**



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The **RIEGL<sup>®</sup> VQ-880-GH** is a fully integrated airborne laser scanning system for combined hydrographic and topographic surveying. The system is offered with integrated and factory-calibrated high-end GNSS/IMU system and up to two cameras. The design allows flexible application of these components to meet specific requirements. Complemented by a **RIEGL** data recorder, the **RIEGL VQ-880-GH** LIDAR system can be installed on various platforms in a straightforward way.

The **RIEGL VQ-880-GH** carries out laser range measurements for high resolution surveying of underwater topography with a narrow, visible green laser beam, emitted from a powerful pulsed laser source. Subject to clarity, at this particular wavelength the laser beam penetrates water enabling measurement of submerged targets.

The distance measurement is based on the time-of-flight measurement with very short laser pulses and subsequent echo digitization and online waveform processing. To handle target situations with most complex multiple echo signals, beside the online waveform processing the digitized echo waveforms can be stored on the **RIEGL** solid state data recorder for subsequent off-line waveform analysis.

The laser beam is deflected in a circular scan pattern and hits the water surface at a nominally constant incidence angle.

The **VQ-880-GH** comprises a high precision inertial measurement sensor for subsequent precise estimation of the instrument's exact location and orientation. Two high-resolution digital cameras and an additional infrared laser scanner are integrated to supplement the data gained by the green laser scanner.

The rugged internal mechanical structure together with the dust- and splash water proof housing enables long-term operation on airborne platforms.

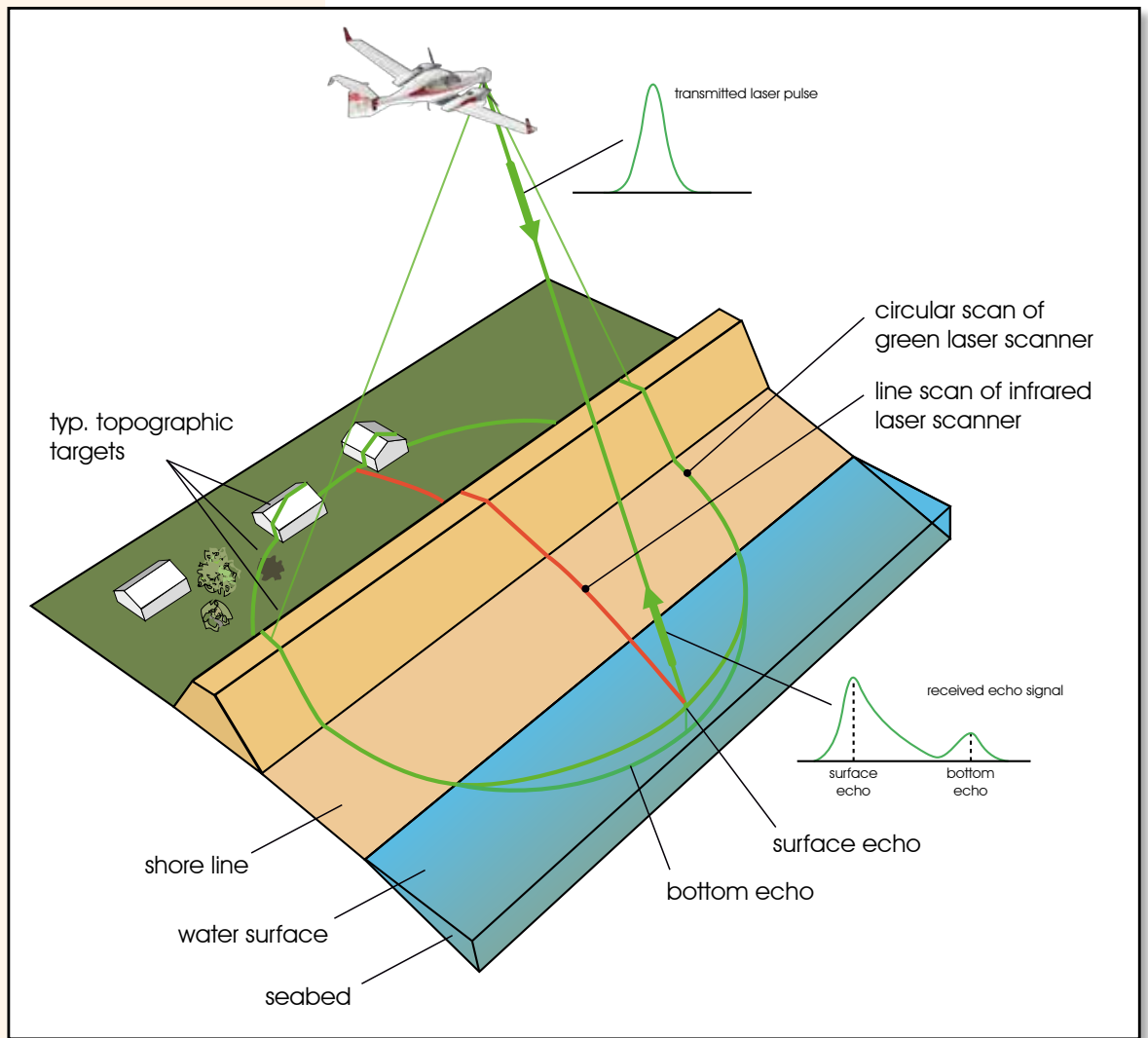
**Typical applications include**

- **coastline and shallow water mapping**
- **acquiring base data for flood prevention**
- **measurement for aggradation zones**
- **habitat mapping**
- **surveying for hydraulic engineering**
- **hydro-archeological-surveying**

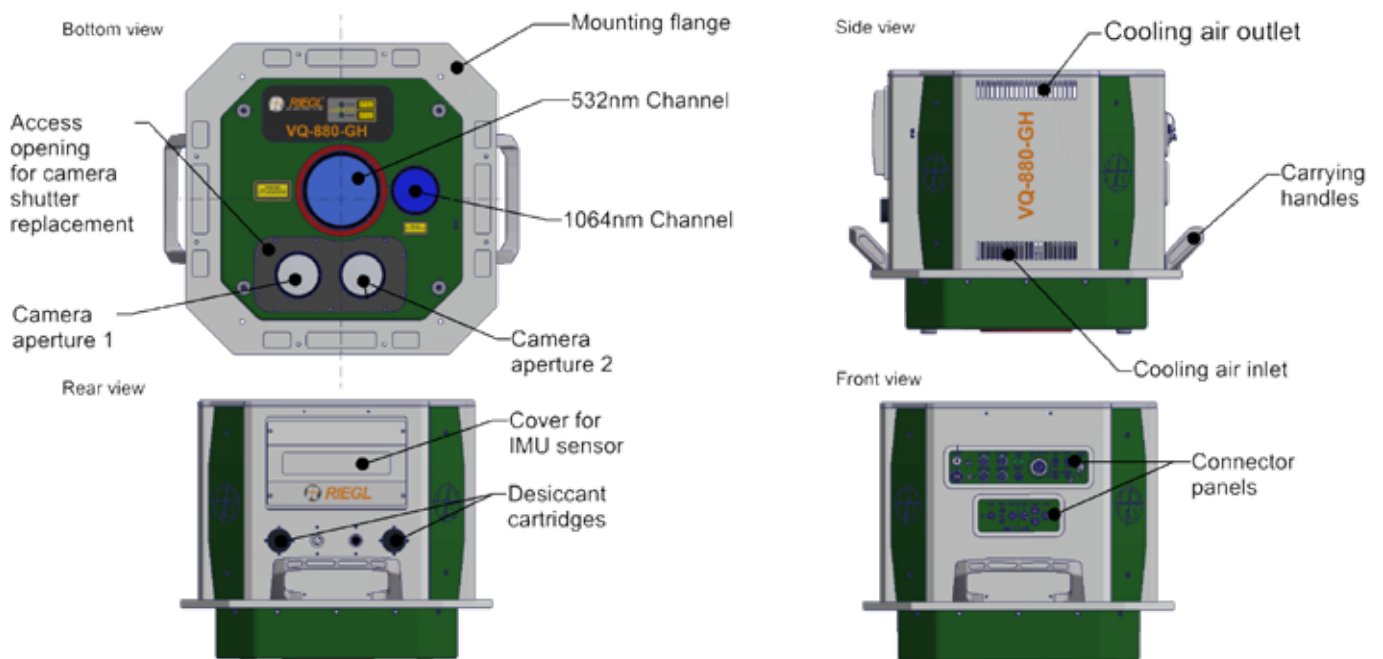


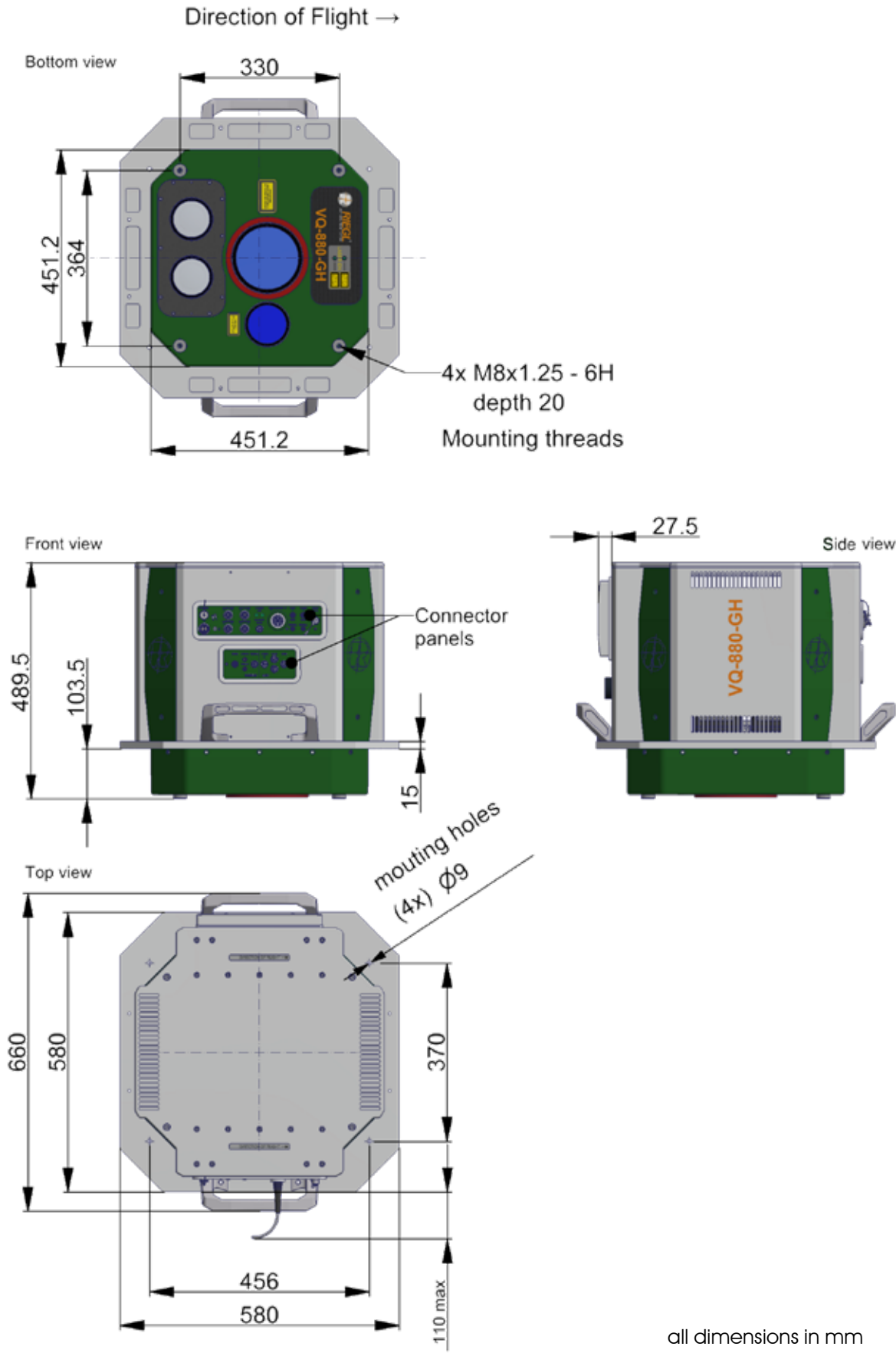
**RIEGL<sup>®</sup>**  
LASER MEASUREMENT SYSTEMS

## RIEGL VQ-880-GH Scan Pattern



## RIEGL VQ-880-GH Elements of Function and Operation





all dimensions in mm

## Important Note:

The following technical data is relevant for a **RIEGL VQ-880-GH Topo-Hydrographic Airborne Laser Scanning System** equipped with an additional Infrared Laser Scanner and is to be seen as a supplement to the Technical Data of the Basic System with Green Laser Scanner.

## Laser Product Classification

Laser Class

for **RIEGL VQ-880-GH** with additional Infrared Laser Scanner

Class 3B Laser Product according to IEC60825-1:2014

The following clause applies for instruments delivered into the United States: Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 50, dated June 24, 2007. The instrument must be used only in combination with the appropriate laser safety box.



NOHD <sup>1)</sup>

1) NOHD ... Nominal Ocular Hazard Distance, based upon MPE according to IEC60825-1:2014, for single pulse condition

175 m <sup>2)</sup>

2) NOHD is determined by green laser scanner. NOHD of the infrared laser scanner: 8 m

## Range Measurement Performance

Measuring Principle

time of flight measurement, echo signal digitization, online waveform processing

Max. Measurement Range <sup>3) 4) 5)</sup>

@ Laser Pulse Repetition Rate

natural targets  $\rho \geq 20\%$

natural targets  $\rho \geq 60\%$

Max. Operating Flight Altitude <sup>6)</sup>

Above Ground Level (AGL)

145 kHz	245 kHz	550 kHz
900 m	700 m	500 m
1500 m	1200 m	850 m
800 m (2600 ft.)	650 m (2130 ft.)	450 m (1480 ft.)

Minimum Range <sup>7)</sup>

Accuracy <sup>8) 10)</sup>

Precision <sup>9) 10)</sup>

Laser Pulse Repetition Rate <sup>11) 12)</sup>

10 m  
25 mm  
25 mm  
up to 550 kHz

Max. Effective Measurement Rate <sup>6) 12)</sup>

45 000 meas./sec (@ 145 kHz PRR & 40° FOV)  
79 000 meas./sec (@ 245 kHz PRR 40° FOV)  
177 200 meas./sec (@ 550 kHz PRR & 40° FOV)

Echo Signal Intensity

Number of Targets per Pulse

Laser Wavelength

Laser Beam Divergence

Laser Beam Footprint (Gaussian Beam Definition)

for each echo signal, high-resolution 16 bit intensity information is provided practically unlimited (details on request) <sup>13)</sup>  
1064 nm (near infrared)  
0.2 mrad <sup>14)</sup>  
22 mm @ 100 m, 105 mm @ 500 m, 200 mm @ 1000 m

## Scanner Performance

Scanning Mechanism / Scan Pattern

Field of View (selectable)

Scan Speed (selectable)

Angular Step Width  $\Delta \theta$  (selectable)

between consecutive laser shots

Angle Measurement Resolution

rotating polygon mirror / curved parallel lines  
 $\pm 20^\circ = 40^\circ$   
10 - 200 scans/sec  
 $0.002^\circ \leq \Delta \theta \leq 0.033^\circ$  (for PRR 550 kHz)

better 0.001° (3.6 arcsec)

- 3) The following conditions are assumed: target larger than the footprint of the laser beam, average ambient brightness, visibility 23 km, perpendicular angle of incidence.
- 4) In bright sunlight, the operational range may be considerably shorter and the operational flight altitude may be considerably lower than under an overcast sky.
- 5) Ambiguity to be resolved by post-processing with RIMTA ALS software.
- 6) Reflectivity  $\rho \geq 20\%$ , 20° FOV, additional roll angle  $\pm 5^\circ$
- 7) Limitations for range measurement capability does not consider laser safety.

- 8) Accuracy is the degree of conformity of a measured quantity to its actual (true) value.
- 9) Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result.
- 10) One sigma @ 150m range under RIEGL test conditions.
- 11) Rounded values.
- 12) User selectable.
- 13) If the laser beam hits, in part, more than one target, the laser's pulse power is split accordingly. Thus, the achievable range is reduced.
- 14) Measured at the  $1/e^2$  points. 0.20 mrad corresponds to an increase of 20 cm of beam diameter per 1000 m distance.

## Export Classification

The Topo-Hydrographic Airborne Laser Scanner VQ-880-GH has been designed and developed for commercial topographic, hydrographic and bathymetric surveying applications.

## Laser Product Classification

Laser Class

The VQ-880-GH is subject to export restrictions as set up by the Wassenaar Arrangement. It is classified as dual-use good according to position number 6A8j3 of the official Dual-Use-List has to be found on site <http://www.wassenaar.org>. Within the European Union, Council Regulation (EC) No 428/2009 implements the export restrictions of the Wassenaar Arrangement. The corresponding position number is **6A008j3**.

## for Basic System with Green Laser Scanner

Class 3B Laser Product according to IEC60825-1:2014

The following clause applies for instruments delivered into the United States: Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 50, dated June 24, 2007. The Instrument must be used only in combination with the appropriate laser safety box.



NOHD <sup>1) 2)</sup>

1) NOHD ... Nominal Ocular Hazard Distance

175 m

2) If it can be assumed that potential viewers are hit by a single pulse only (e.g., when the instrument is mounted on a platform moving so fast that the pulses do not overlap at the NOHD.)

## Range Measurement Performance

Measuring Principle

time of flight measurement, echo signal digitization, online waveform processing, full waveform recording for post processing

Hydrography

Typ. Measurement Range <sup>3)</sup>

Typ. Operating Flight Altitude <sup>5)</sup>

Above Ground Level (AGL)

1.5 Secchi depth for bright ground ( $\rho \geq 80\%$ ) <sup>4)</sup>  
600 m (1970 ft.)

Topography (diffusely reflecting targets)

Max. Measurement Range <sup>6) 7) 8)</sup>

natural targets  $\rho \geq 20\%$

natural targets  $\rho \geq 60\%$

Typ. Operating Flight Altitude <sup>8) 5)</sup>

Above Ground Level (AGL)

2500 m  
3600 m  
2200 m (7200 ft.)

Minimum Range

Accuracy <sup>9) 11)</sup>

Precision <sup>10) 11)</sup>

Laser Pulse Repetition Rate

Max. Effective Measurement Rate <sup>5)</sup>

Echo Signal Intensity

Number of Targets per Pulse

Laser Wavelength

Laser Beam Divergence

Laser Beam Footprint (Gaussian Beam Definition)

10 m  
25 mm  
25 mm  
up to 550 kHz <sup>5)</sup>  
up to 550 000 meas./sec (@ 550 kHz PRR)  
for each echo signal, high-resolution 16 bit intensity information is provided  
online waveform processing: up to 9, depending on measurement program <sup>12)</sup>  
532 nm, green  
selectable, 0.7 up to 2.0 mrad <sup>13)</sup>  
100 mm @ 100 m, 500 mm @ 500 m, 1000 mm @ 1000 m <sup>14)</sup>

## Scanner Performance

Scanning Mechanism / Scan Pattern

Field of View (selectable)

Scan Speed (selectable)

Angular Step Width  $\Delta \theta$  (selectable)

between consecutive laser shots

Angle Measurement Resolution

rotating prism / circular  
 $\pm 20^\circ = 40^\circ$   
10 - 80 revolutions/sec, equivalent to 20 - 160 scans/sec  
 $0.007^\circ \leq \Delta \theta \leq 0.052^\circ$  (for PRR 550 kHz)

better 0.001° (3.6 arcsec)

## IMU/GNSS Performance <sup>15) 16)</sup>

IMU Accuracy <sup>17)</sup>

Roll, Pitch

Heading

IMU Sampling Rate

Position Accuracy (typ.)

horizontal / vertical

0.0025°  
0.005°  
200 Hz  
<0.05 m / <0.1 m

3) The Secchi depth is defined as the depth at which a standard black and white disc deployed into the water is no longer visible to the human eye.

4) at typ. operating flight altitude

5) rounded values

6) The following conditions are assumed: target larger than the footprint of the laser beam, average ambient brightness, visibility 23 km, perpendicular angle of incidence, ambiguity to be resolved multiple-time-around processing.

7) In bright sunlight, the operational range may be considerably shorter than under an overcast sky.

8) Reflectivity  $\rho \geq 20\%$ , 40° FOV, additional roll angle  $\pm 5^\circ$

9) Accuracy is the degree of conformity of a measured quantity to its actual (true) value.

10) Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result.

11) Topography, one sigma @ 150m range under RIEGL test conditions.

12) If the laser beam hits, in part, more than one target, the laser's pulse power is split accordingly. Thus, the achievable range is reduced.

13) Measured at the 1/e<sup>2</sup> points. 1.0 mrad corresponds to an increase of 100 mm of beam diameter per 100 m distance.

14) The laser beam footprint values correspond to a beam divergence of 1mrad.

15) The INS configuration of the RIEGL VQ-880-GH Laser Scanning System can be modified to the customer's requirements.

16) The installed IMU is listed neither in the European Export Control List (i.e. Annex 1 of Council Regulation 428/2009) nor in the Canadian Export Control List. Detailed information on certain cases will be provided on request.

17) one sigma values, no GNSS outages, post-processed during base station data

## Integrated Digital Cameras <sup>1)</sup>

### RGB Camera

Sensor Resolution  
Sensor Dimensions (diagonal)  
Focal Length of Camera Lens  
Field of View (FOV)  
Interface  
Data Storage

up to 100 MPixel CMOS without FMC<sup>2)</sup> or up to 80 MPixel CCD with FMC<sup>2)</sup>  
67.2 mm (medium format)  
50 mm  
approx. 56.2° x 43.7°  
USB 3.0  
separate dedicated data recorder

## Data Interfaces

Configuration  
Scan Data Output

GNSS Interface <sup>3)</sup>

LAN 10/100/1 000 Mbit/sec  
LAN 10/100/1 000 Mbit/sec,  
High Speed Serial Dual Glass Fiber Link to RIEGL Data Recorder  
Serial RS232 interface for data string with GNSS-time information,  
TTL input for 1 PPS synchronization pulse

## General Technical Data

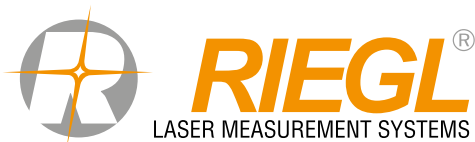
Power Supply Input Voltage  
Power Consumption

Main Dimensions (LxWxH)  
Weight  
Humidity  
Protection Class Scan Head  
Max. Flight Altitude <sup>5)</sup>  
operating  
not operating)  
Temperature Range  
operation / storage

18 - 32 V DC  
typ. 330 W (without IMU/GNSS/cameras)  
typ. 370 W (with IMU/GNSS/cameras) <sup>4)</sup>  
max. 400 W  
489.5 mm x 660 mm x 580 mm, mounting flange 580 mm x 580 mm  
approx. 70 kg (with IMU/GNSS/cameras and optional infrared laser scanner)  
non condensing  
IP54, dust and splash-proof  
  
16 500 ft (5 000 m) above Mean Sea Level (MSL)  
18 000 ft (5 500 m) above MSL  
  
0°C up to +40°C / -10°C up to +50°C

1) The camera configuration of the RIEGL VQ-880-GH Laser Scanning System can be modified to the customer's requirements.  
2) Forward Motion Compensation

3) to be used for external GNSS receiver  
4) @ 20°C ambient temperature, 100 kHz PRR, 100 scans/sec  
5) For standard atmospheric conditions: 1013 mbar, +15°C at sea level



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