

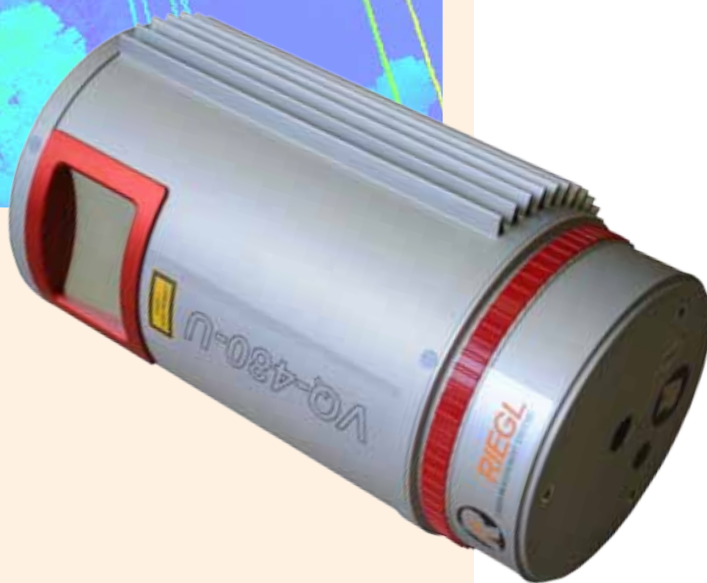
RIEGL VQ-480-U

- **high-accuracy ranging based on echo digitization and online waveform processing**
- **high laser repetition rate - fast data acquisition**
- **multiple target capability - unlimited number of targets**
- **perfectly linear scan lines**
- **compact, rugged and very lightweight design**
- **electrical interfaces for GPS data string and Sync Pulse (1PPS)**
- **mechanical interface for IMU mounting**
- **integrated LAN-TCP/IP interface**

The V-Line® Airborne Laser Scanner **RIEGL VQ-480-U** provides high speed data acquisition using a narrow infrared laser beam and a fast line scanning mechanism. High-accuracy laser ranging is based on **RIEGL's** unique echo digitization and online waveform processing, which allows achieving superior measurement results even under adverse atmospheric conditions, and the evaluation of multiple target echoes.

The scanning mechanism is based on a fast rotating multi-facet polygonal mirror, which provides fully linear, unidirectional and parallel scan lines.

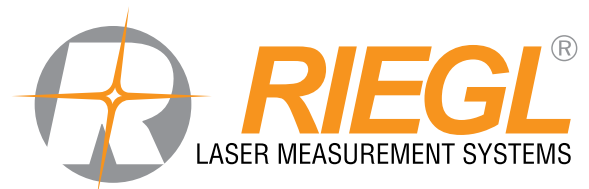
The **RIEGL VQ-480-U** is a very lightweight and compact laser scanner, mountable in any orientation and even under limited space conditions on motorized hang-gliders, gyrocopters, ultra-light aircrafts and UAVs. The instrument has a low power consumption, needs only a single voltage supply and provides line scan data via integrated LAN-TCP/IP interface. An external storage device can also be connected via the USB interface.



Typical applications include

- **Terrain Mapping**
- **Power Line, Railway Track, and Pipeline Inspection**
- **Capturing the Topography in Open-Cast Mining Areas**
- **Cultural Heritage Mapping**

visit our website
www.riegl.com



Laser Product Classification

Class 1 Laser Product according to IEC60825-1:2007

The following clause applies for instruments delivered into the United States:
Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant
to Laser Notice No. 50, dated June 24, 2007.



Range Measurement Performance

Measuring Principle

time of flight measurement, echo signal digitization,
online waveform processing, multiple-time-around-processing

Laser Pulse Repetition Rate PRR ¹⁾	50 kHz	100 kHz	200 kHz	300 kHz	400 kHz	550 kHz
Effective Measurement Rate (meas./sec.) ^{1) 2)}	25 000	50 000	100 000	150 000	200 000	275 000
Max. Measuring Range ^{3) 4)}						
natural targets $\rho \geq 20\%$	950 m	650 m	500 m	400 m	350 m	300 m
natural targets $\rho \geq 60\%$	1500 m	1100 m	800 m	650 m	600 m	500 m
Max. Operating Flight Altitude AGL ^{1) 2)}	750 m (2450 ft)	550 m (1800 ft)	400 m (1300 ft)	350 m (1150 ft)	300 m (1000 ft)	250 m (800 ft)
Max. Number of Targets per Pulse	practically unlimited (details on request)					

1) Rounded values.
2) Reflectivity $\rho \geq 20\%$, $\pm 30^\circ$ FOV, additional roll angle $\pm 5^\circ$.
3) The following conditions are assumed: target larger than the footprint of the laser beam, perpendicular angle of incidence, visibility 23 km, average ambient brightness.
4) Ambiguity to be resolved by post-processing with RiMTA software.

Minimum Range

Accuracy ^{5) 7)}

Precision ^{6) 7)}

Laser Pulse Repetition Rate ^{1) 8)}

Max. Effective Measurement Rate ¹⁾

Echo Signal Intensity

Laser Wavelength

Laser Beam Divergence ⁹⁾

Laser Beam Footprint (Gaussian Beam Definition)

10 m

25 mm

25 mm

up to 550 kHz

up to 275 000 meas./sec. (@ 550 kHz PRR & 60° FOV)

for each echo signal, high-resolution 16 bit intensity information is provided

near infrared

0.3 mrad

31 mm @ 100 m, 75 mm @ 250 m, 150 mm @ 500 m

- 5) Accuracy is the degree of conformity of a measured quantity to its actual (true) value.
6) Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result.

- 7) One sigma @ 150 m range under *RIEGL* test conditions.
8) User selectable.
9) Measured at the $1/e^2$ points. 0.30 mrad corresponds to an increase of 30 mm of beam diameter per 100 m distance.

Scanner Performance

Scanning Mechanism

Field of View (selectable)

Scan Speed (selectable)

Angular Step Width $\Delta \theta$ (selectable)

between consecutive laser shots

Angle Measurement Resolution

Internal Sync Timer

Scan Sync (optional)

rotating polygon mirror

$60^\circ (+30^\circ / -30^\circ)$

10 - 150 scans/sec

$0.002^\circ \leq \Delta \theta \leq 0.36^\circ$

0.001°

for real-time synchronized time stamping of scan data
scanner rotation synchronization

Data Interfaces

Configuration

Scan Data Output

GPS-System

LAN 10/100/1000 Mbit/sec

LAN 10/100/1000 Mbit/sec, USB 2.0

Serial RS232 interface for data string with GPS-time information,

TTL input for 1PPS synchronization pulse

Mechanical Interfaces

Mounting of the Laser Scanner

Mounting of IMU sensor

3 x M6 thread inserts in the front and the rear plate

3 x M6 thread inserts in the front plate

(rigidly coupled with the internal mechanical structure)

General Technical Data

Power Supply Input Voltage

Current Consumption

Main Dimensions

Weight

Humidity

Protection Class

Max. Flight Altitude (operating)

Max. Flight Altitude (not operating)

Temperature Range

18 - 32 V DC

typ. 55 W

348 x 183 mm (length x diameter)

approx. 7.5 kg (without optional mounting frame; weight mounting frame: approx. 1 kg)

max. 80 % non condensing @ $+31^\circ\text{C}$

IP64, dust and splash-proof

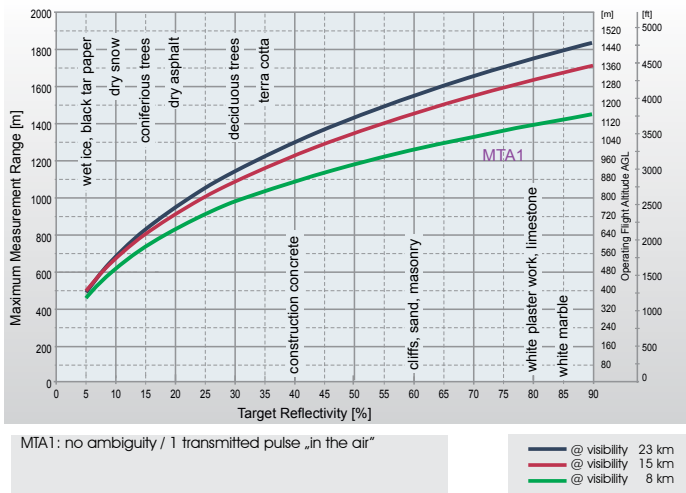
16 500 ft (5 000 m) above MSL

18 000 ft (5 500 m) above MSL

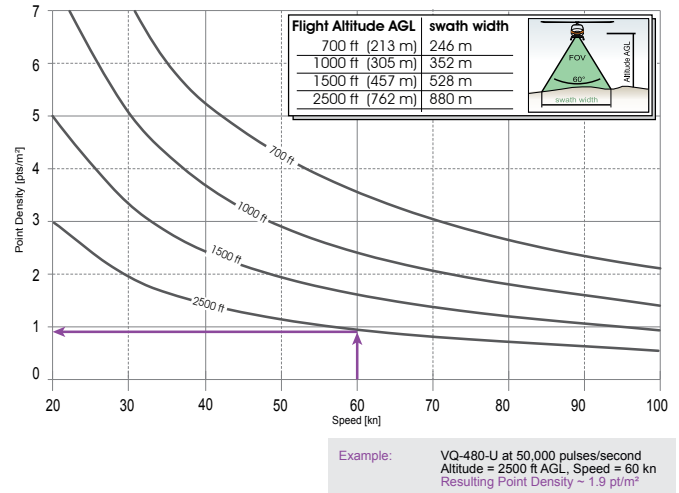
0°C up to $+40^\circ\text{C}$ (operation) / -20°C up to $+50^\circ\text{C}$ (storage)

Maximum Measurement Range & Point Density *RIEGL VQ®-480-U*

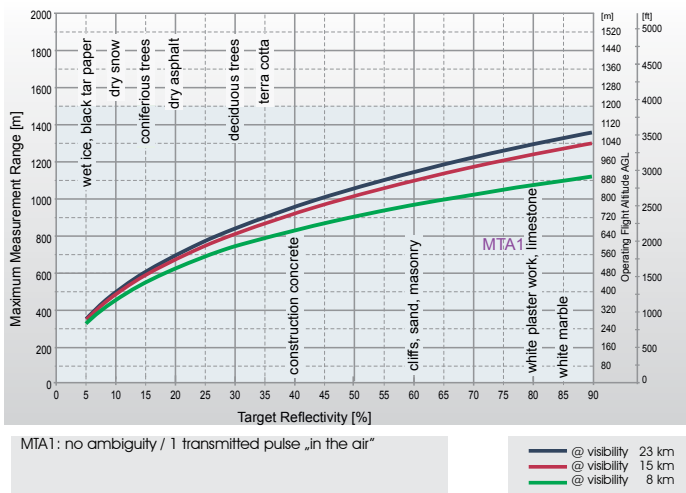
PRR = 50 kHz



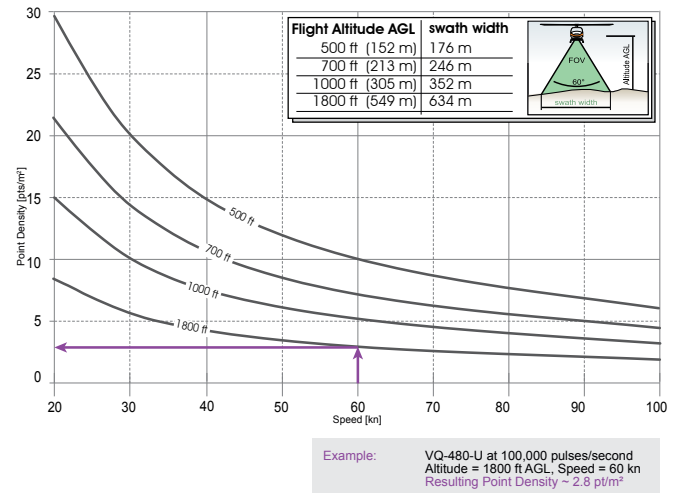
PRR = 50 kHz



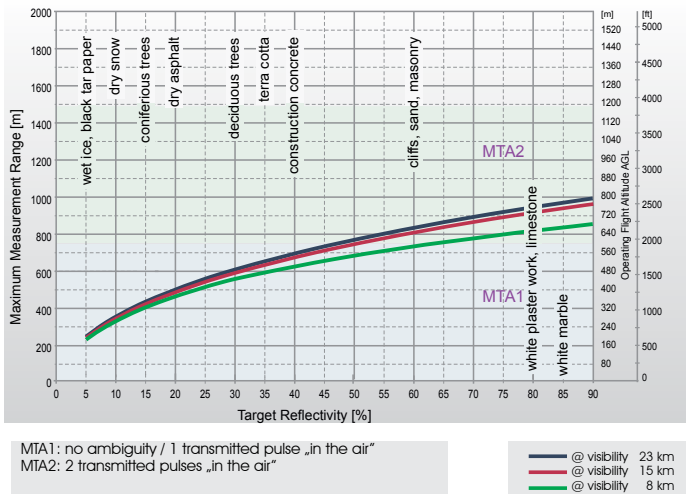
PRR = 100 kHz



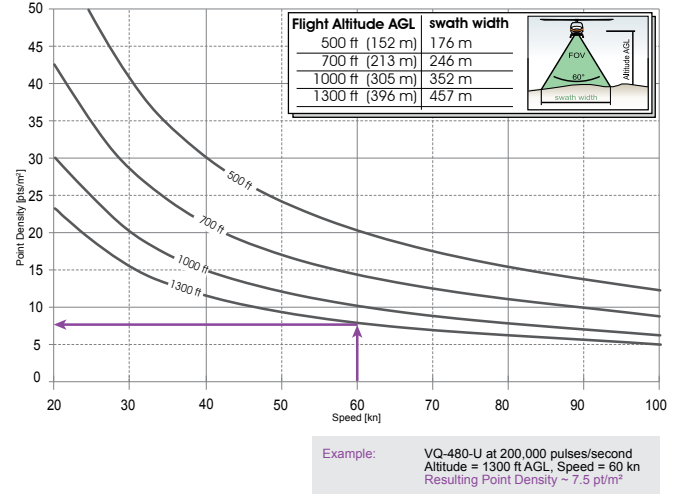
PRR = 100 kHz



PRR = 200 kHz



PRR = 200 kHz

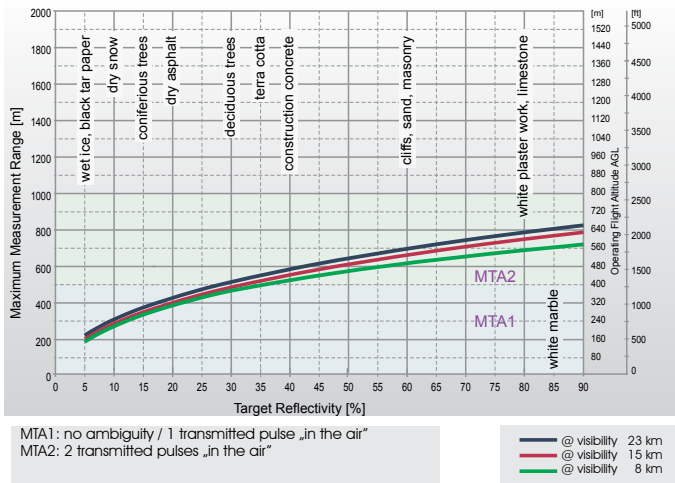


The following conditions are assumed for the Operating Flight Altitude AGL

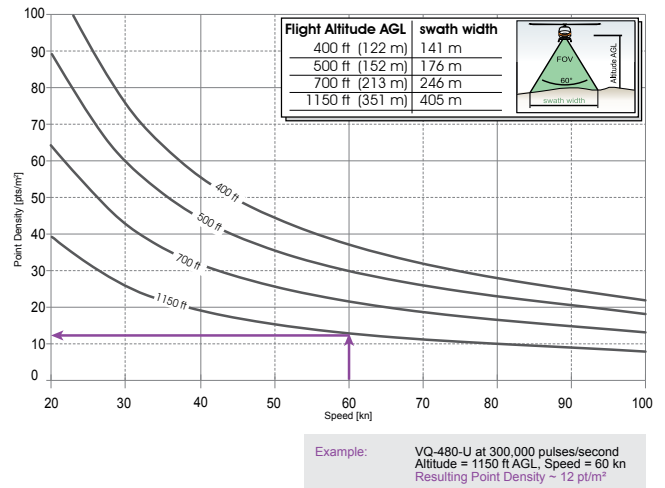
- ambiguity resolved by multiple-time-around (MTA) processing & flight planning
- target size $\geq$ laser footprint
- scan angle 60°
- average ambient brightness
- roll angle $\pm 5^\circ$

Maximum Measurement Range & Point Density *RIEGL VQ®-480-U*

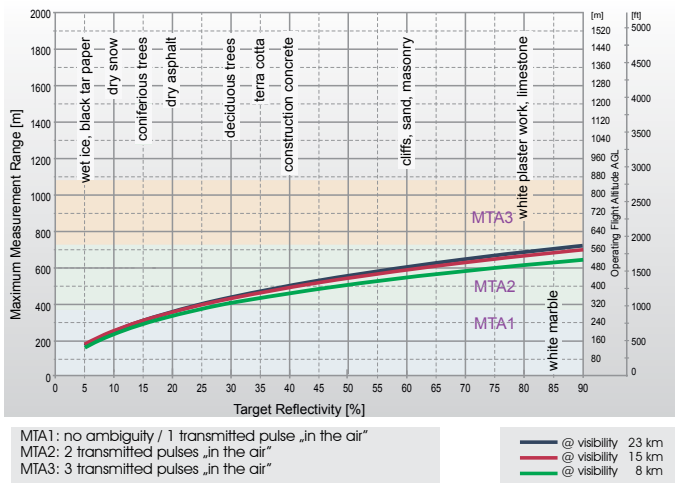
PRR = 300 kHz



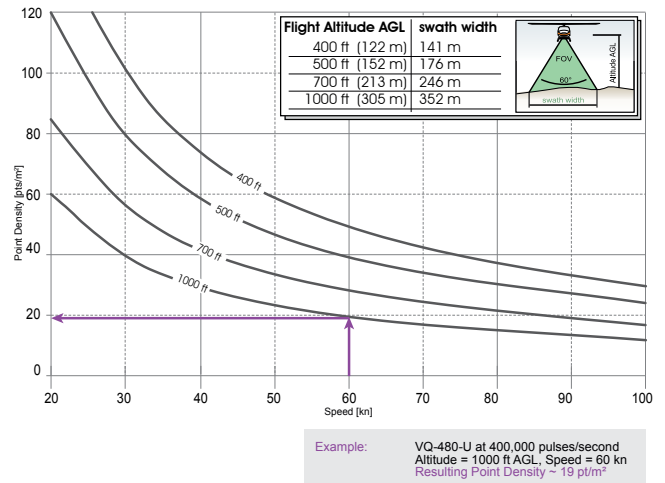
PRR = 300 kHz



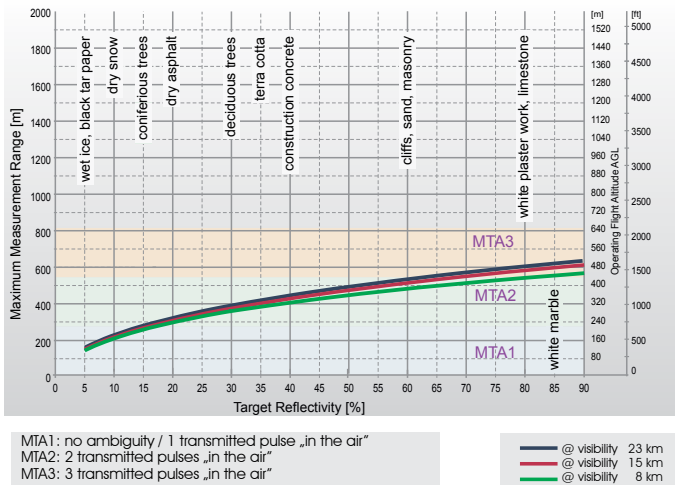
PRR = 400 kHz



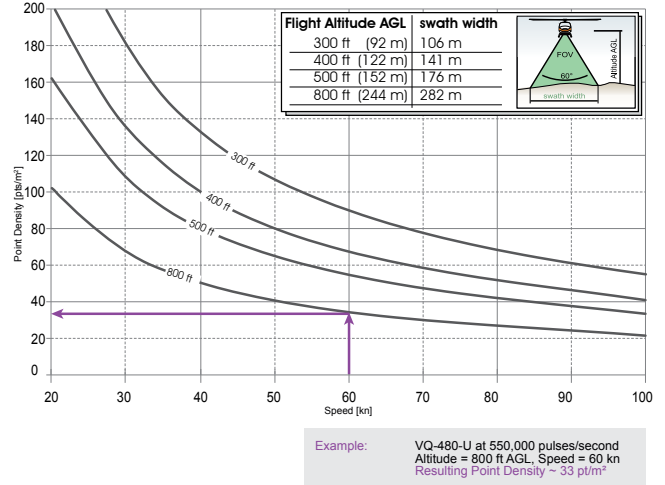
PRR = 400 kHz



PRR = 550 kHz



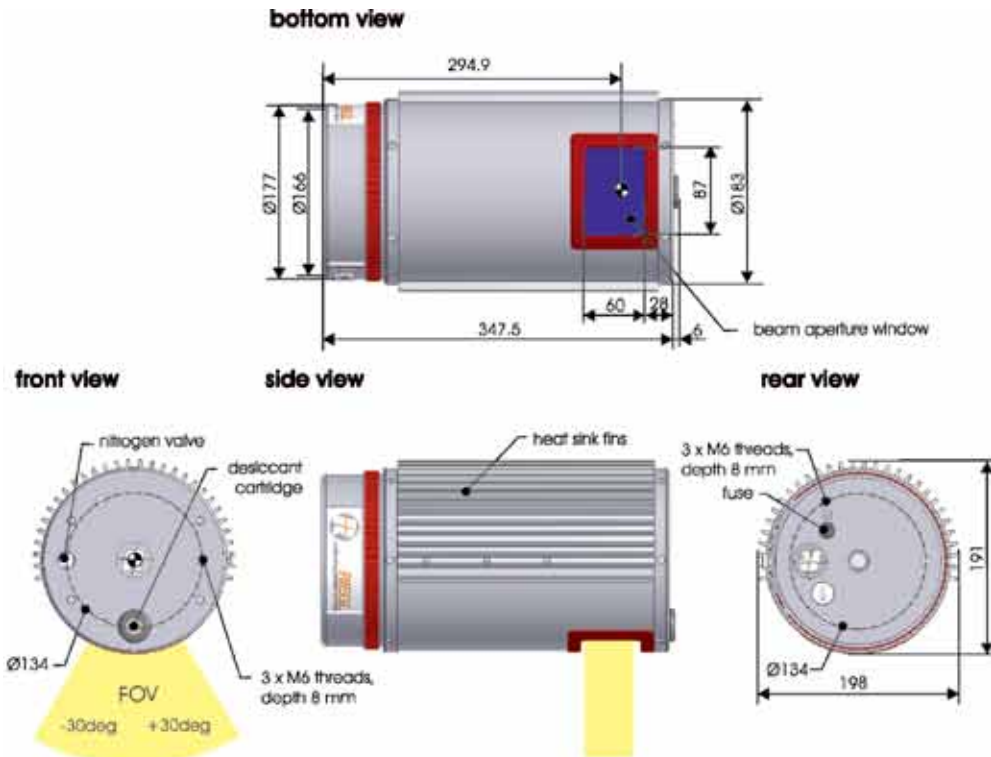
PRR = 550 kHz



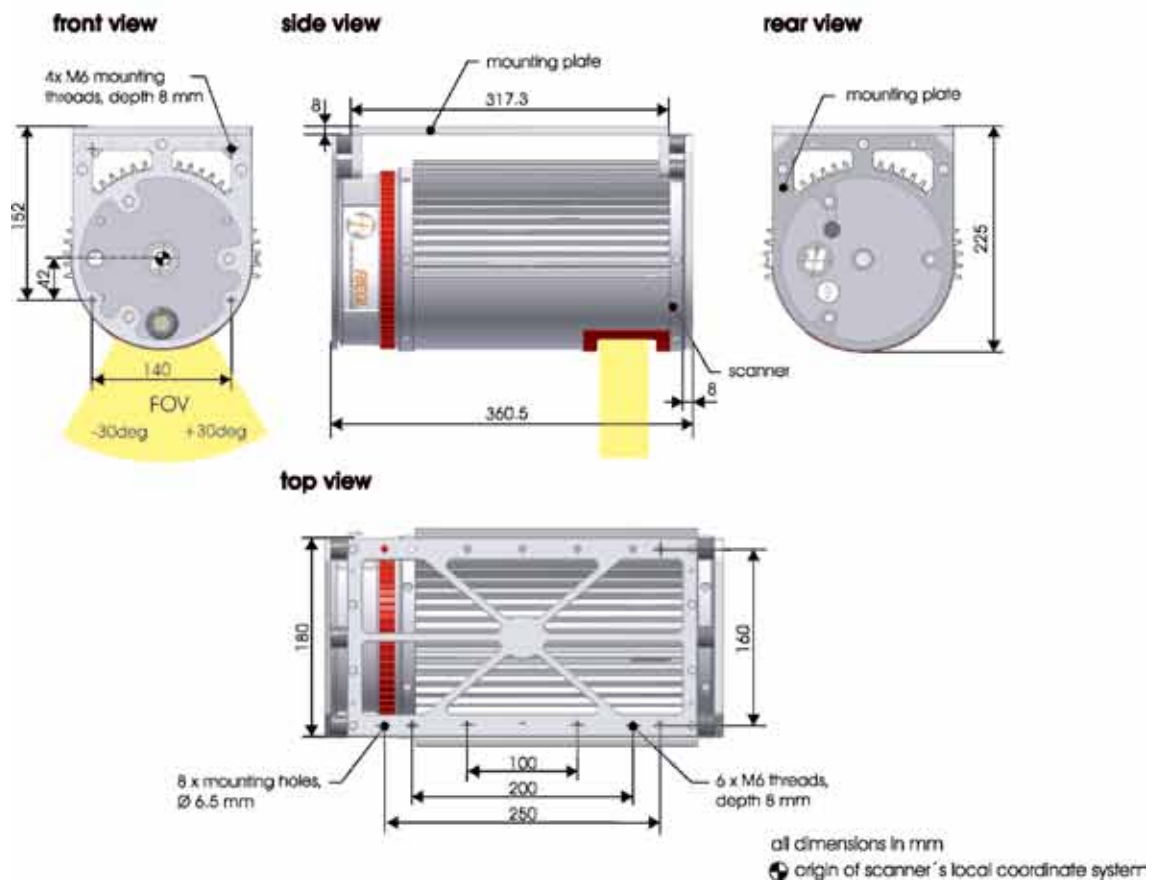
The following conditions are assumed for the Operating Flight Altitude AGL

- ambiguity resolved by multiple-time-around (MTA) processing & flight planning
- target size $\geq$ laser footprint
- scan angle 60°
- average ambient brightness
- roll angle $\pm 5^\circ$

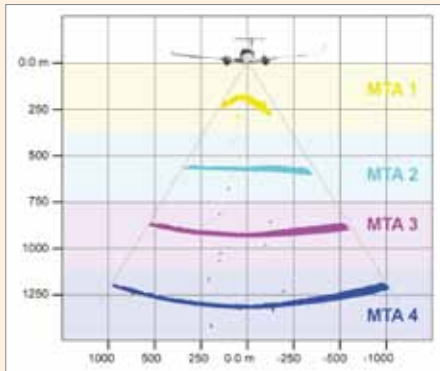
Dimensional Drawings *RIEGL VQ®-480-U* without Mounting Frame



Dimensional Drawings *RIEGL VQ®-480-U* with Mounting Frame



Multiple-time-around Data Acquisition and Processing



In time-of-flight laser ranging a maximum unambiguous measurement range exists, which is defined by the laser pulse repetition rate and the speed of light. In case the echo signal of an emitted laser pulse arrives later than the emission of the subsequently emitted laser pulse, the range result becomes ambiguous - an effect known as „**Multiple-Time-around**“ (MTA).

The *RIEGL* VQ-480-U allows ranging beyond the maximum unambiguous measurement range using a sophisticated modulation scheme applied to the train of emitted laser pulses. The dedicated post-processing software RIMTA provides algorithms for multiple-time-around processing, which automatically assign definite range results to the correct MTA zones without any further user interaction required.



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