

Full Waveform Digitizing, Dual Channel Airborne Laser Scanner for Ultra Wide Area Mapping

RIEGL LMS-Q1560

- high laser pulse repetition rate up to 800 kHz
- digitization electronics for full waveform data
- innovative forward/backward looking capability
- single multifacet polygon mirror for beam deflection
- integrated multi-megapixel aerial medium format camera
- integrated secondary camera (e.g. IR-camera)
- integrated inertial navigation system and GNSS receiver
- fiber coupled high speed data interface to single RIEGL Data Recorder
- single power supply
- various interfaces to external cameras, GNSS etc.
- mounting flange for interfacing with typical hatches and stabilized platforms
- compact and robust housing

The new high performance, fully integrated long-range airborne laser scanner system *RIEGL LMS-Q1560* is a cutting-edge tool for a variety of airborne surveying missions. The two channel scanner makes use of a powerful laser source, multiple-time-around (MTA) processing, echo digitization and waveform analysis. This combination allows the operation at varying flight altitudes and is therefore ideally suited for aerial survey of ultra wide areas as well as of complex urban environments.

The *RIEGL LMS-Q1560* can be operated at a maximum pulse repetition rate of 800 kHz providing an effective measurement rate of 530,000 measurements on the ground, and operates at an altitude of up to 15,500 ft. Usually occurring range ambiguities at this measurement rate are automatically resolved by *RIEGL's* multiple time around processing software RiMTA, handling up to 10 pulses in the air, simultaneously. This enables the user to do effective flight planning even for difficult terrain, reducing the flying time significantly. The system allows the user to plan safe flights with sufficient clearance to terrain.

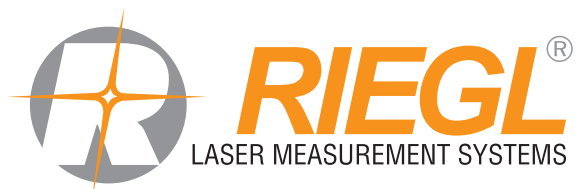
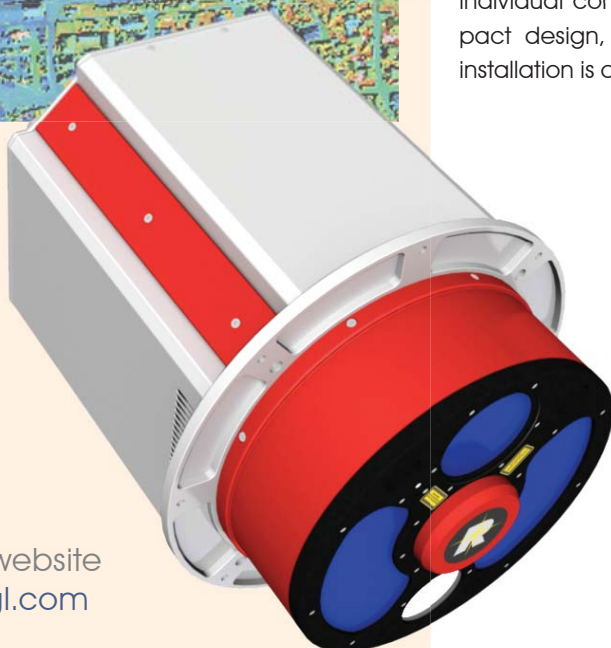
The *RIEGL LMS-Q1560* comes with a unique and innovative forward/backward looking capability. This enables capturing data from multiple angles more effectively and more accurately at high point density, along with a 60 degree field of view (FOV).

The system is equipped with a seamlessly integrated IMU/GNSS system. Optionally, an already available IMU sensor may be easily integrated; making the *RIEGL LMS-Q1560* a cost-effective solution for system upgrades. An 80 megapixel aerial camera and the capability to integrate a secondary aerial camera complete the system. With all individual components integrated into one single instrument of compact design, suited for gyro-stabilized leveling mounts, the system installation is outstandingly easy and straight-forward.

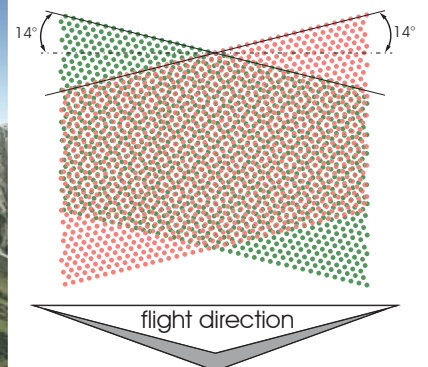
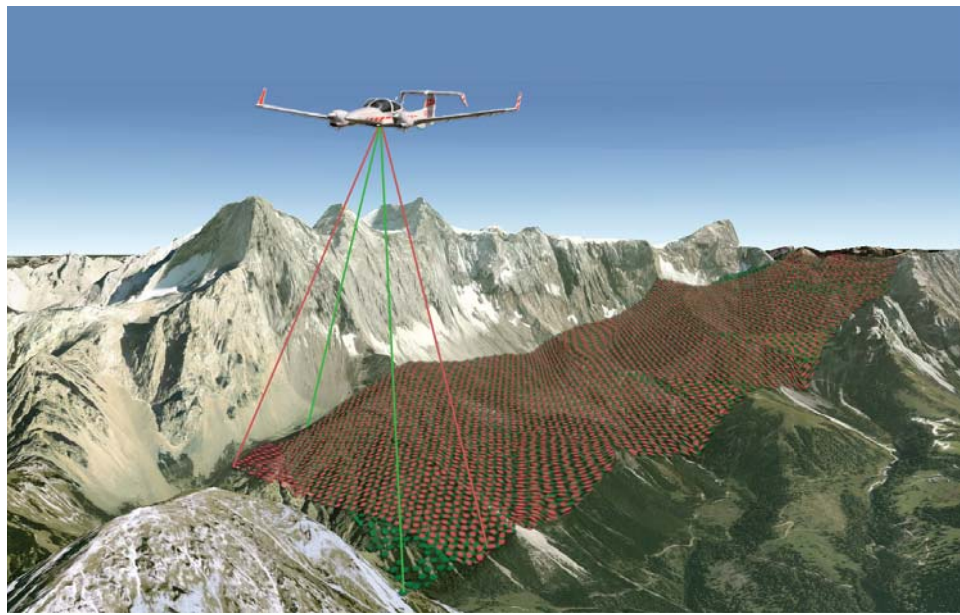
Applications:

- Ultra Wide Area / High Altitude Mapping
- Mapping of Complex Urban Environments
- Glacier & Snowfield Mapping
- City Modeling
- Mapping of Lakesides & River Banks
- Agriculture & Forestry
- Corridor Mapping

visit our website
www.riegl.com



RIEGL LMS-Q1560 Scan Pattern



Each channel delivers straight parallel scan lines. The scan lines of the two channels are tilted against each other by 28 degrees providing an optimum distribution of the measurements of a two-channel system on the ground invariant to changes in terrain height.

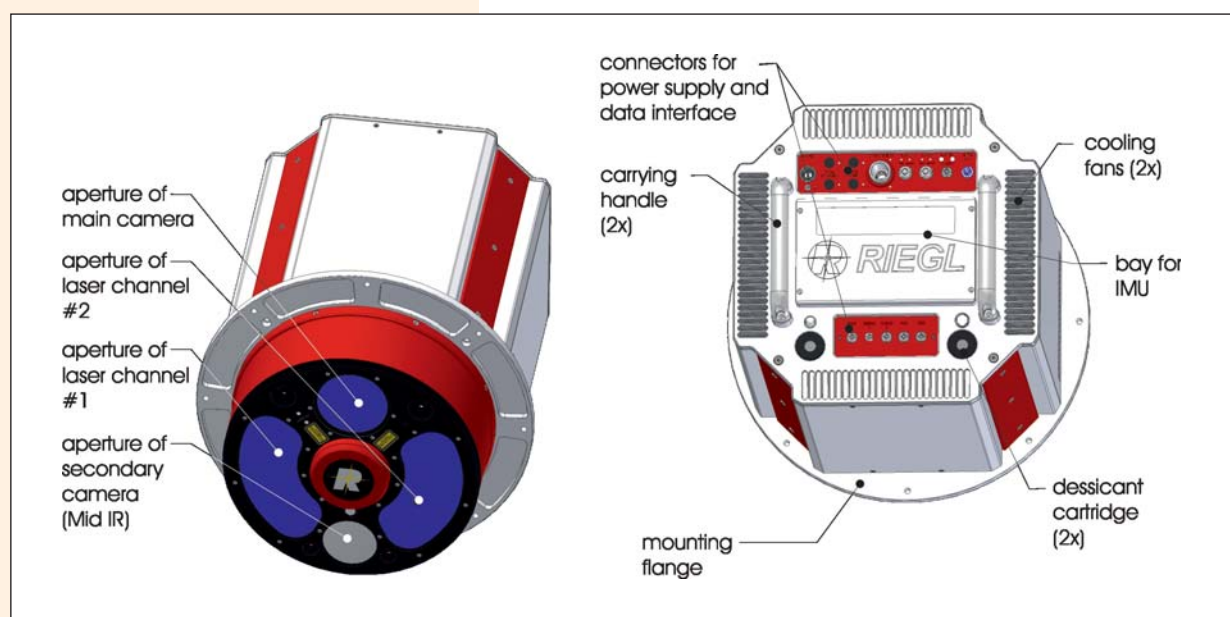
Tilt Angle of Scan Lines

+/- 14°

Forward/Backward Look in Non-Nadir Direction

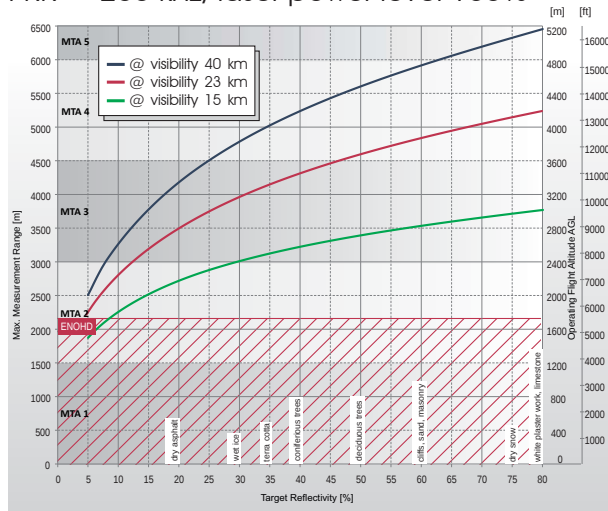
+/- 8° at the edges

RIEGL LMS-Q1560 Housing

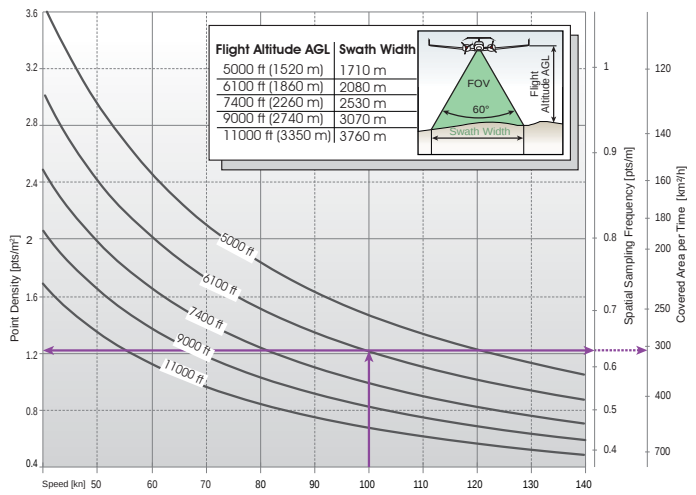


Measurement Range & Point Density *RIEGL* LMS-Q1560

PRR = 200 kHz, laser power level 100%

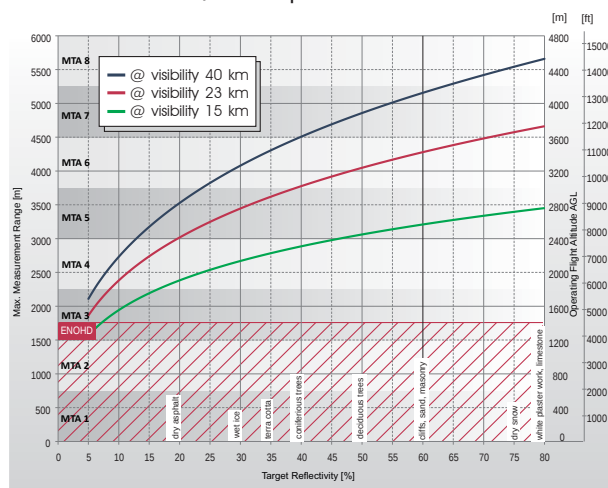


Example: LMS-Q1560 at 200,000 pulses/sec, laser power level 100%
Altitude = 6100ft AGL, Speed = 100 kn

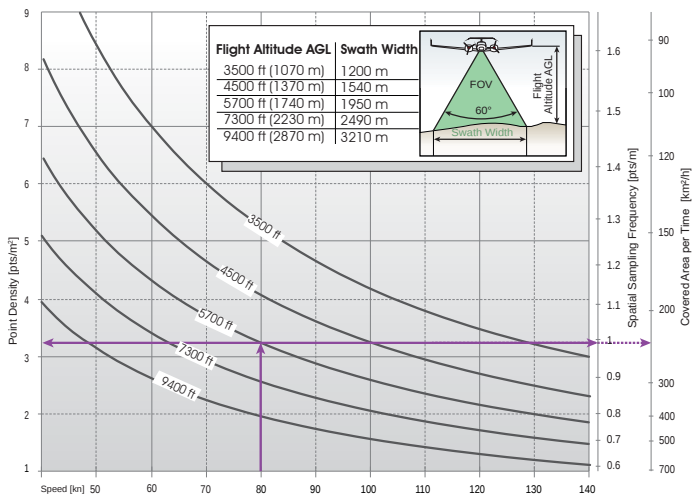


Results: Point Density ~ 1.2 pts/m²
Spatial Sampling Frequency ~ 0.62 pts/m
Covered Area per Time ~ 310 km²/h

PRR = 400 kHz, laser power level 100%

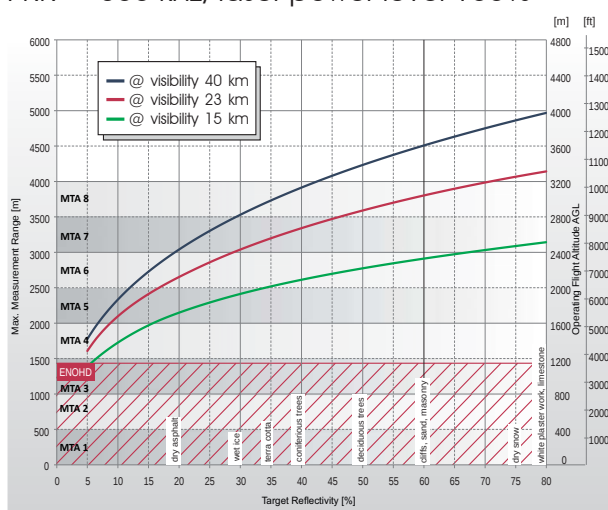


Example: LMS-Q1560 at 400,000 pulses/sec, laser power level 100%
Altitude = 5700ft AGL, Speed = 80 kn

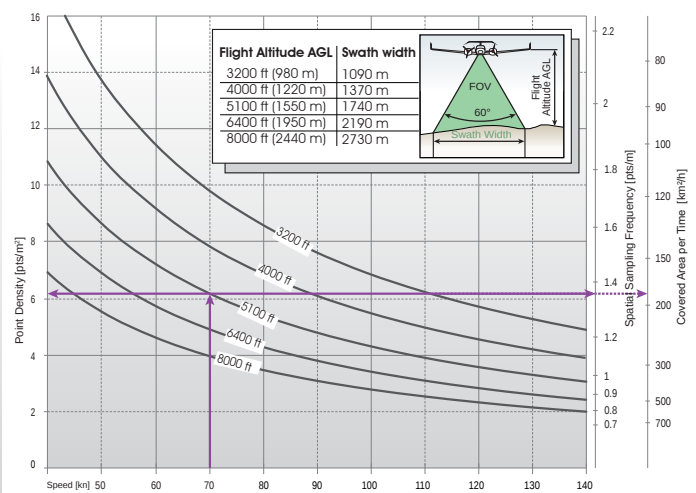


Results: Point Density ~ 3.2 pts/m²
Spatial Sampling Frequency ~ 1 pts/m
Covered Area per Time ~ 250 km²/h

PRR = 600 kHz, laser power level 100%



Example: LMS-Q1560 at 600,000 pulses/sec, laser power level 100%
Altitude = 5100ft AGL, Speed = 70 kn



Results: Point Density ~ 6.2 pts/m²
Spatial Sampling Frequency ~ 1.38 pts/m
Covered Area per Time ~ 180 km²/h

The following conditions are assumed for the Operating Flight Altitude AGL

- ambiguity resolved by multiple-time-around (MTA) processing & flight planning
- target size ≥ laser footprint
- scan angle 60°
- average ambient brightness
- roll angle ±5°

Definition of the Spatial Sampling Frequency

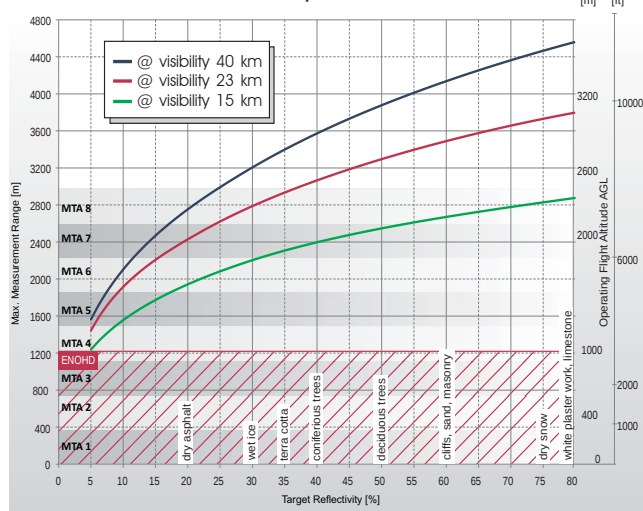
- The Spatial Sampling Frequency is the reciprocal of the 95th percentile of the distribution function of the maximum distances between neighboring scan points.
- When considering any individual scan point, the probability to find its most distant neighbor within the reciprocal of the Spatial Sampling Frequency is 95%.

Assumptions for calculation of the Covered Area per Time

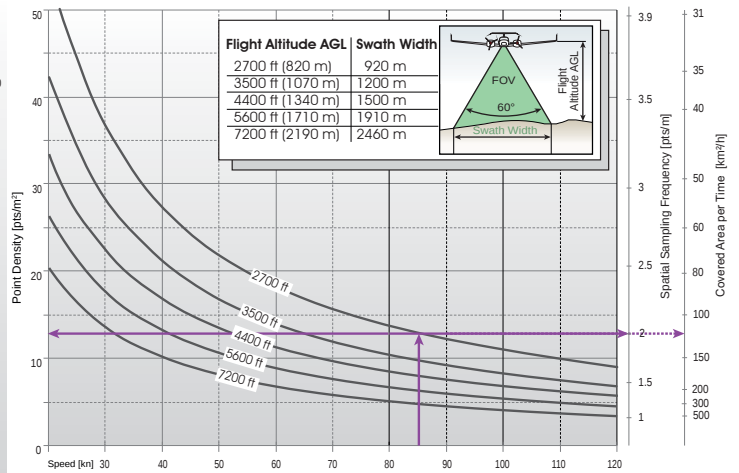
- 20% overlap of neighboring flight strips. This overlap covers a roll angle of ±5° or a reduction of flight altitude AGL of 20%.

Measurement Range & Point Density *RIEGL* LMS-Q1560

PRR = 800 kHz, laser power level 100%

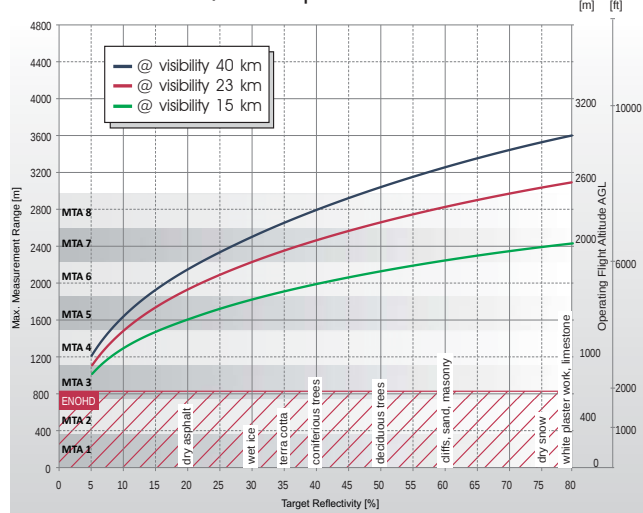


Example: LMS-Q1560 at 800,000 pulses/sec, laser power level 100%
Altitude = 2700ft AGL, Speed = 85 km/h

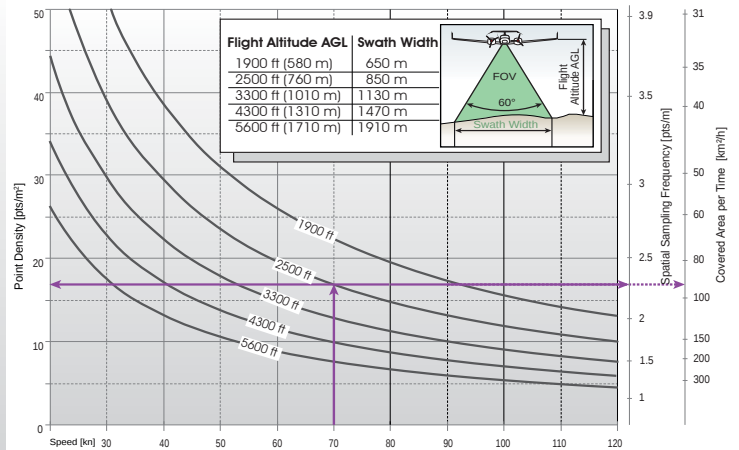


Results: Point Density ~ 12.8 pts/m²
Spatial Sampling Frequency ~ 2 pts/m
Covered Area per Time ~ 120 km²/h

PRR = 800 kHz, laser power level 50%

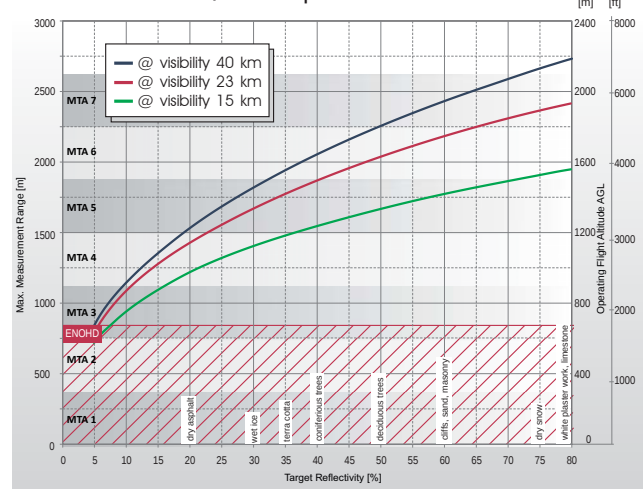


Example: LMS-Q1560 at 800,000 pulses/sec, laser power level 50%
Altitude = 2500ft AGL, Speed = 70 km/h

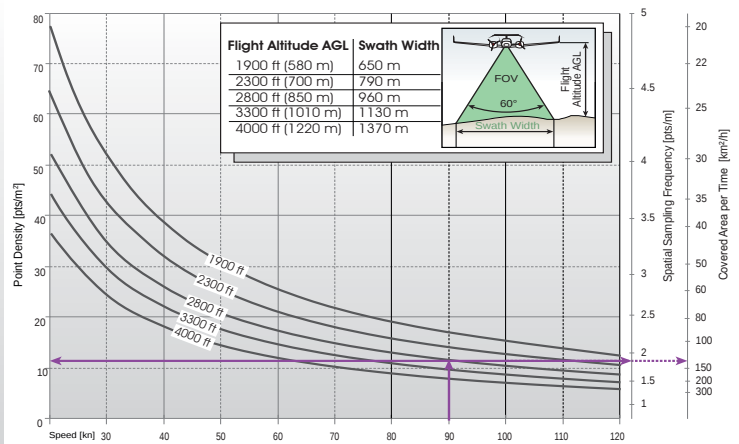


Results: Point Density ~ 16.8 pts/m²
Spatial Sampling Frequency ~ 2.2 pts/m
Covered Area per Time ~ 95 km²/h

PRR = 800 kHz, laser power level 25%



Example: LMS-Q1560 at 800,000 pulses/sec, laser power level 25%
Altitude = 2800ft AGL, Speed = 90 km/h



Results: Point Density ~ 11.6 pts/m²
Spatial Sampling Frequency ~ 1.8 pts/m
Covered Area per Time ~ 140 km²/h

The following conditions are assumed for the Operating Flight Altitude AGL

- ambiguity resolved by multiple-time-around (MTA) processing & flight planning
- target size ≥ laser footprint
- scan angle 60°
- average ambient brightness
- roll angle ±5°

Definition of the Spatial Sampling Frequency

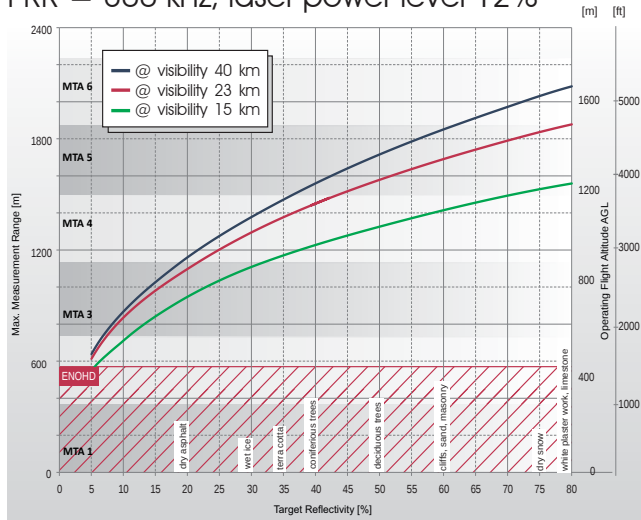
- The Spatial Sampling Frequency is the reciprocal of the 95th percentile of the distribution function of the maximum distances between neighboring scan points. When considering any individual scan point, the probability to find its most distant neighbor within the reciprocal of the Spatial Sampling Frequency is 95%.

Assumptions for calculation of the Covered Area per Time

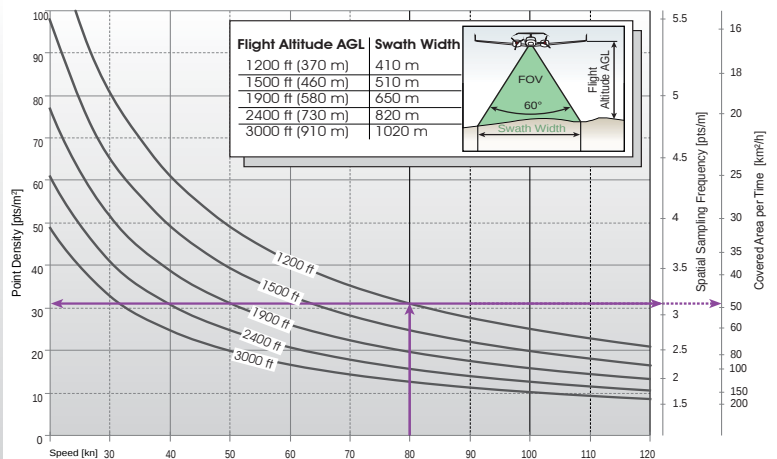
- 20% overlap of neighboring flight strips. This overlap covers a roll angle of ±5° or a reduction of flight altitude AGL of 20%.

Measurement Range & Point Density RIEGL LMS-Q1560

PRR = 800 kHz, laser power level 12%

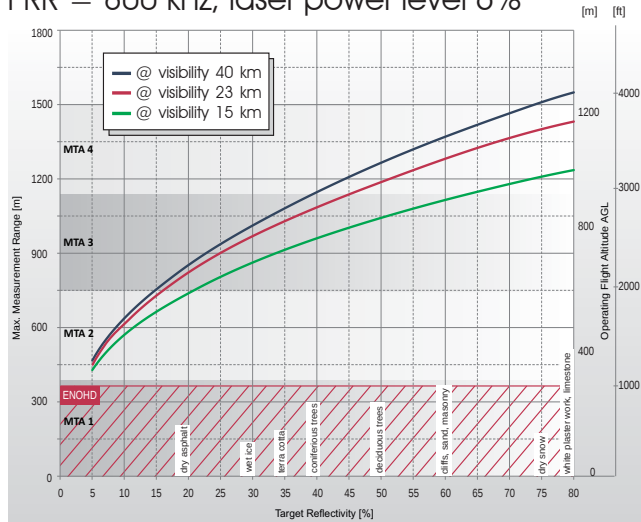


Example: LMS-Q1560 at 800,000 pulses/sec, laser power level 12%
Altitude = 1200ft AGL, Speed = 80 kn

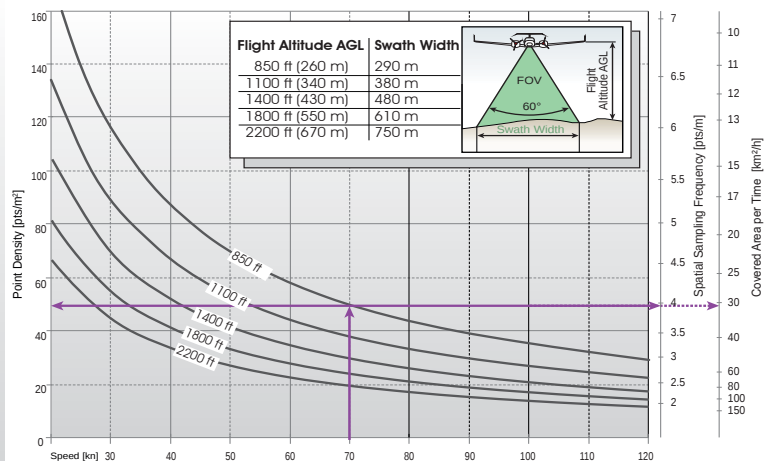


Results: Point Density ~ 31 pts/m²
Spatial Sampling Frequency ~ 3.1 pts/m
Covered Area per Time ~ 49 km²/h

PRR = 800 kHz, laser power level 6%



Example: LMS-Q1560 at 800,000 pulses/sec, laser power level 6%
Altitude = 850ft AGL, Speed = 70 kn



Results: Point Density ~ 49.4 pts/m²
Spatial Sampling Frequency ~ 4 pts/m
Covered Area per Time ~ 31 km²/h

The following conditions are assumed for the Operating Flight Altitude AGL

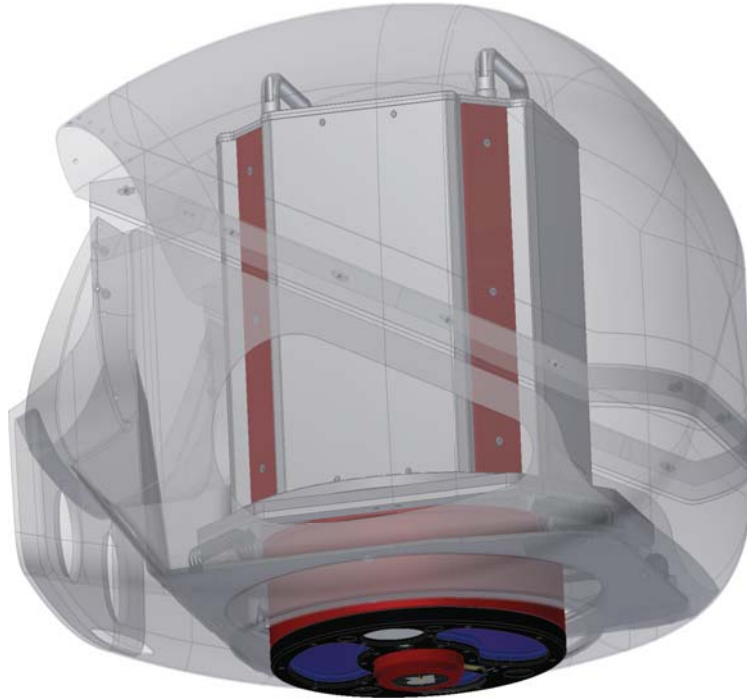
- ambiguity resolved by multiple-time-around (MTA) processing & flight planning
- target size ≥ laser footprint
- scan angle 60°
- average ambient brightness
- roll angle ±5°

Definition of the Spatial Sampling Frequency

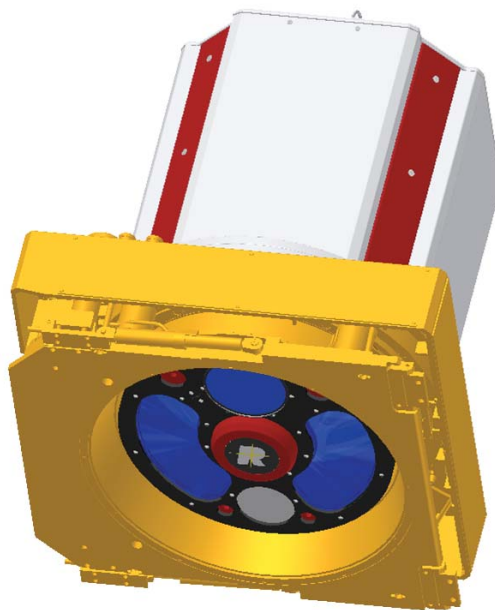
- The Spatial Sampling Frequency is the reciprocal of the 95th percentile of the distribution function of the maximum distances between neighboring scan points. When considering any individual scan point, the probability to find its most distant neighbor within the reciprocal of the Spatial Sampling Frequency is 95%.

Assumptions for calculation of the Covered Area per Time

- 20% overlap of neighboring flight strips. This overlap covers a roll angle of ±5° or a reduction of flight altitude AGL of 20%.



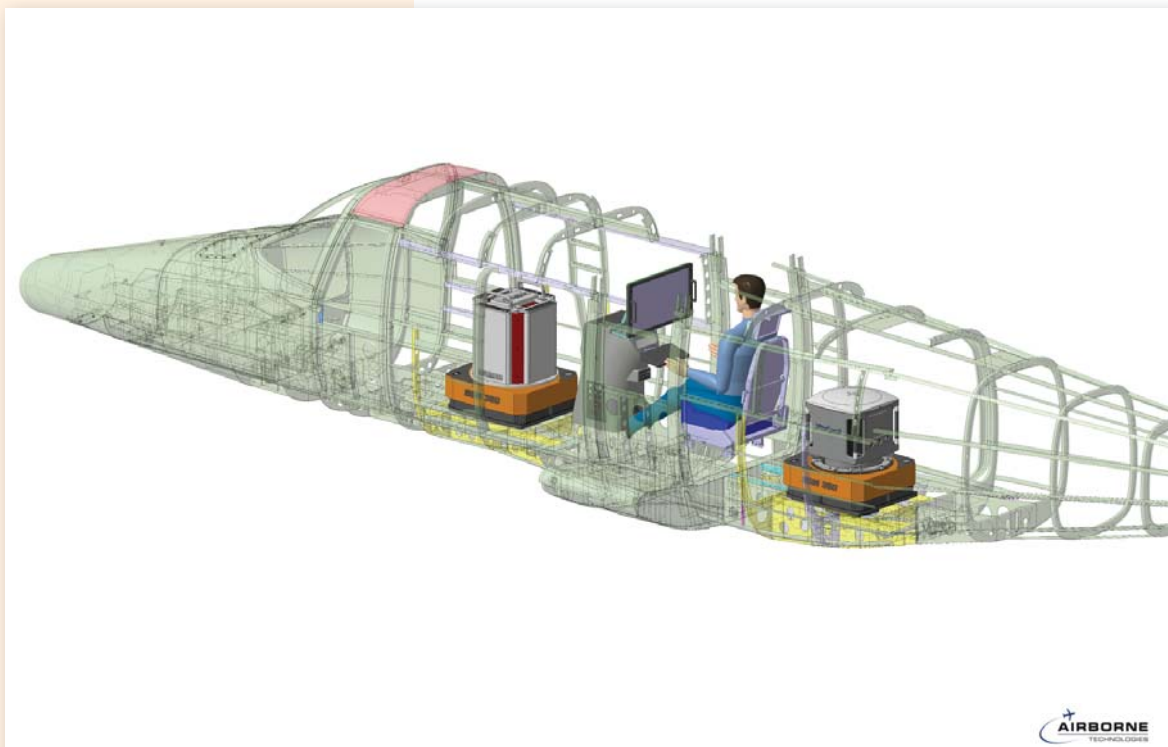
RIEGL LMS-Q1560 installed in the nose pod of fixed-wing aircraft
DA42 MPP



RIEGL LMS-1560 installed on GSM-3000 stabilized platform to
be used in a helicopter or fixed-wing aircraft



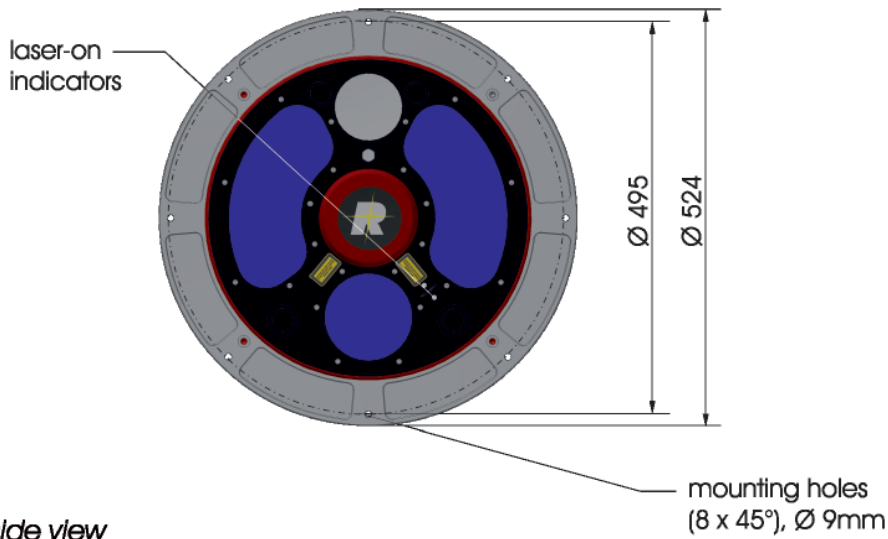
RIEGL LMS-Q1560 installed on GSM-3000 stabilized platform in the fixed-wing aircraft **TECNAM MMA**



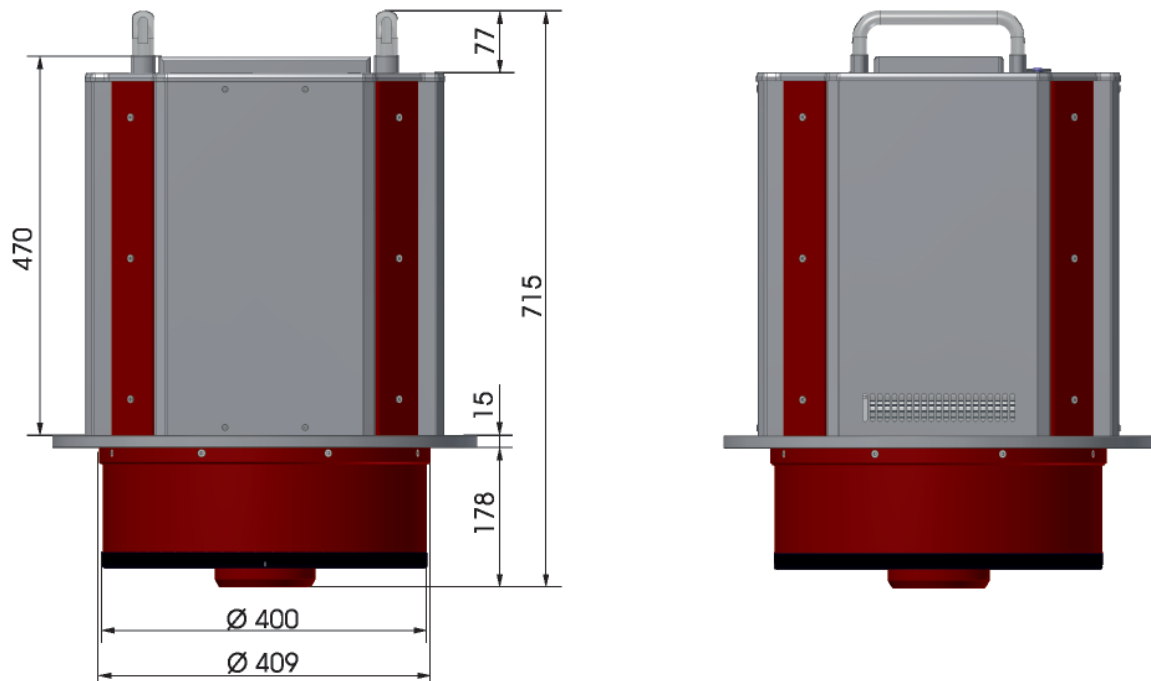
RIEGL LMS-Q1560 installed on GSM-3000 stabilized platform in the fixed-wing aircraft **A-VIATOR AP68PT-600**

RIEGL LMS-Q1560 Main Dimensions

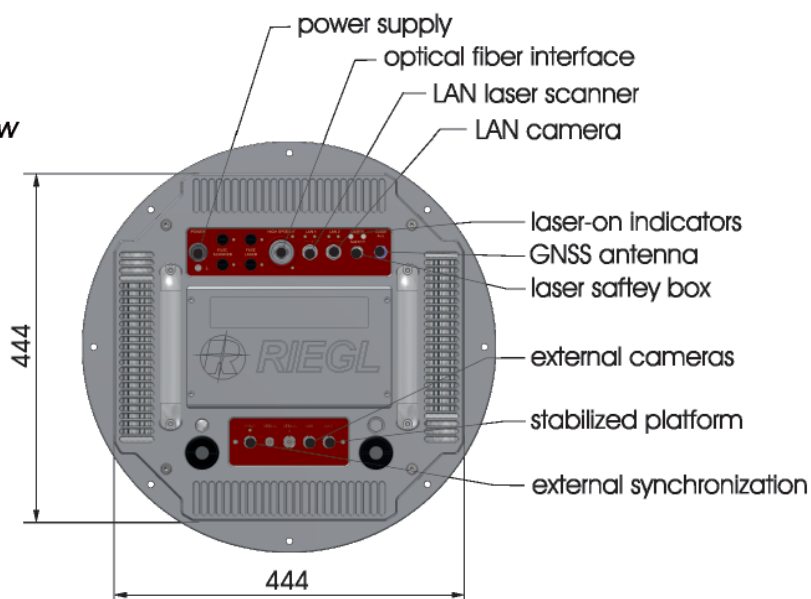
bottom view



side view



top view



all dimensions in mm

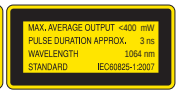
Technical Data *RIEGL* LMS-Q1560

Laser Product Classification

Class 3B Laser Product according to IEC60825-1:2007

The following clause applies for instruments delivered into the United States: Complies with 21 CFR 1040.10 and 1040.11 except for deviations pursuant to Laser Notice No. 50, dated June 24, 2007.

The instrument must be used only in combination with the appropriate laser safety box.



Range Measurement Performance

Full Laser Power

Laser Power Level	100%			
Laser Pulse Repetition Rate (PRR)	200 kHz	400 kHz	600 kHz	800 kHz
Max. Measuring Range ^{1) 3)}				
natural targets $\rho \geq 20\%$	4100 m	3500 m	3000 m	2700 m
natural targets $\rho \geq 60\%$	5800 m	5100 m	4500 m	4100 m
Max. Operating Flight Altitude Above Ground Level (AGL) ^{2) 3)}	4700 m 15500 ft	4200 m 13700 ft	3700 m 12000 ft	3300 m 11000 ft
NOHD ⁴⁾	290 m	240 m	190 m	160 m
ENOH ⁵⁾	2200 m	1770 m	1440 m	1240 m
1) The following conditions are assumed: • target is larger than the footprint of the laser beam • average ambient brightness • visibility 40 km • perpendicular angle of incidence • ambiguity resolved by multiple-time-around processing 2) Reflectivity $\rho \geq 60\%$, max. scan angle 60°, additional roll angle $\pm 5^\circ$ 3) In bright sunlight the operational range may be considerably shorter and the operational flight altitude may be considerably lower than under an overcast sky. 4) Nominal Ocular Hazard Distance, based upon MPE according to IEC60825-1:2007, for single pulse condition 5) Extended Nominal Ocular Hazard Distance, based upon MPE according to IEC60825-1:2007, for single pulse condition				

Reduced Laser Power

Laser Power Level	50%	25%	12%	6%
Laser Pulse Repetition Rate (PRR)	800 kHz	800 kHz	800 kHz	800 kHz
Max. Measuring Range ^{6) 8)}				
natural targets $\rho \geq 20\%$	2100 m	1500 m	1120 m	820 m
natural targets $\rho \geq 60\%$	3200 m	2400 m	1800 m	1350 m
Max. Operating Flight Altitude Above Ground Level (AGL) ^{7) 8)}	2600 m 8600 ft	1950 m 6400 ft	1450 m 4800 ft	1100 m 3600 ft
NOHD ⁹⁾	110 m	105 m	70 m	45 m
ENOH ¹⁰⁾	860 m	840 m	570 m	370 m
6) The following conditions are assumed: • target is larger than the footprint of the laser beam • average ambient brightness • visibility 40 km • perpendicular angle of incidence • ambiguity resolved by multiple-time-around processing 7) Reflectivity $\rho \geq 60\%$, max. scan angle 60°, additional roll angle $\pm 5^\circ$ 8) In bright sunlight the operational range may be considerably shorter and the operational flight altitude may be considerably lower than under an overcast sky. 9) Nominal Ocular Hazard Distance, based upon MPE according to IEC60825-1:2007, viewing a single scan line 10) Extended Nominal Ocular Hazard Distance, based upon MPE according to IEC60825-1:2007, viewing a single scan line				

Minimum Range ¹¹⁾

Accuracy ^{12) 13)}

Precision ^{12) 14)}

Laser Pulse Repetition Rate

Effective Measurement Rate

Laser Wavelength

Laser Beam Divergence ¹⁵⁾

Number of Targets per Pulse

50 m

20 mm

20 mm

up to 800 kHz

up to 532 kHz @ 60° scan angle

near infrared

≤ 0.25 mrad

digitized waveform processing: unlimited ¹⁶⁾

monitoring data output: first pulse

Scanner Performance

Scanning Mechanism

Scan Pattern

Tilt Angle of Scan Lines

Forward/ Backward Look in Non-Nadir Direction

Scan Angle Range

Scan Speed

Angular Step Width $\Delta\theta$ ¹⁹⁾

Angle Measurement Resolution

Scan Sync

rotating polygon mirror

parallel scan lines per channel, crossed scan lines between channels

$\pm 14^\circ$

$\pm 8^\circ$ at the edges

$\pm 30^\circ = 60^\circ$ total

28 - 400 lines/sec¹⁷⁾ @ laser power level $\geq 50\%$

20 - 400 lines/sec¹⁸⁾ @ laser power level $< 50\%$

$\Delta\theta \geq 0.012^\circ$ @ laser power level $\geq 50\%$

$\Delta\theta \geq 0.006^\circ$ @ laser power level $< 50\%$

0.001°

Option for synchronizing scan lines to external timing signal

11) Limitation for range measurement capability, does not consider laser safety!

12) Standard deviation one sigma @ 250 m range under *RIEGL* test conditions.

13) Accuracy is the degree of conformity of a measured quantity to its actual (true) value.

14) Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result.

15) Measured at the $1/e^2$ points. 0.25 mrad correspond to an increase of 25 cm of beam diameter per 1000 m distance.

16) Practically limited only by the maximum data rate allowed for the *RIEGL* Data Recorder.

17) Minimum scan speed increasing linearly to 106 lines/sec @ 800 000 Hz PRR @ laser power $\geq 50\%$

18) Minimum scan speed increasing linearly to 54 lines/sec @ 800 000 Hz PRR @ laser power $< 50\%$

19) Angle between consecutive laser shots within a scan line, user adjustable

Technical Data *RIEGL LMS-Q1560 (continued)*

Intensity Measurement

For each echo signal, high-resolution 16-bit intensity information is provided which can be used for target discrimination and/or identification/classification.

Data Interfaces

Configuration
Monitoring Data Output
Digitized Data Output
Synchronization

TCP/IP Ethernet (10/100 MBit)
TCP/IP Ethernet (10/100 MBit)
Dual glass fiber data link to *RIEGL* Data Recorder DR1560
Serial RS232 interface, TTL input for 1 pps synchronization pulse,
accepts different data formats for GNSS-time information

General Technical Data

Power Supply / Current Consumption
Main Dimensions (L x W x H)
Weight

Protection Class
Max. Flight Altitude operating / not operating
Temperature Range

18 - 32 V DC / approx. 10 A @ 24 VDC
444 x 444 x 715 mm, mounting flange diameter 524 mm
approx. 60 kg without optional components
approx. 67 kg with optional components
IP54
18500 ft (5600 m) above Mean Sea Level MSL / 18500 ft (5600 m) above MSL
0°C up to +40°C (operation) / -10°C up to +50°C (storage)

Optional Components LMS-Q1560

Please note: The INS and the camera configuration of the *RIEGL LMS-Q1560* Laser Scanning System can be modified to the customer's requirements.

Integrated Digital Cameras

RGB Camera

Sensor Resolution
Sensor Dimensions (diagonal)
Focal Length of Camera Lens
Field of View (FOV)
Interface
Data Storage

80 MPixel
67.2 mm (medium format)
55 mm
approx. 52° x 40°
USB 3.0
via GigE to *RIEGL* Data Recorder DR1560

Infrared Camera

Spectral Range
Sensor Resolution
Sensor Dimensions (diagonal)
Focal Length of Camera Lens
Field of View (FOV)
Interface
Data Storage

7.5 - 14 μ m
640 x 480 Pixel
13.6 mm
13.1 mm
approx. 45° x 34°
GigE
via GigE to *RIEGL* Data Recorder DR1560

Integrated IMU/GNSS ¹⁾

IMU Accuracy ²⁾
Roll, Pitch
Heading
IMU Sampling Rate
Position Accuracy (typ.)

0.005°
0.008°
200 Hz
0.05 m - 0.3 m

1) The installed IMU is listed neither in the European Export Control List (i.e. Annex 1 of Council Regulation 428/2009) nor in the Canadian Export Control List. Detailed information on certain cases will be provided on request.

2) One sigma values, no GNSS outages, post-processed with base station data



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